CHAPTER2

Concepts in Structural Steel Design

2.1 DESIGN PHILOSOPHIES

As discussed earlier, the design of a structural member entails the selection of a cross section that will safely and economically resist the applied loads. Economy usually means minimum weight—that is, the minimum amount of steel. This amount corresponds to the cross section with the smallest weight per foot, which is the one with the smallest cross-sectional area. Although other considerations, such as ease of construction, may ultimately affect the choice of member size, the process begins with the selection of the lightest cross-sectional shape that will do the job. Having established this objective, the engineer must decide how to do it safely, which is where different approaches to design come into play. The fundamental requirement of structural design is that the required strength not exceed the available strength; that is,

Required strength \leq available strength

In *allowable strength design* (ASD), a member is selected that has cross-sectional properties such as area and moment of inertia that are large enough to prevent the maximum applied axial force, shear, or bending moment from exceeding an allowable, or permissible, value. This allowable value is obtained by dividing the nominal, or theoretical, strength by a factor of safety. This can be expressed as

Required strength \leq allowable strength (2.1)

where

Allowable strength = $\frac{\text{nominal strength}}{\text{safety factor}}$

Strength can be an axial force strength (as in tension or compression members), a flexural strength (moment strength), or a shear strength.

If stresses are used instead of forces or moments, the relationship of Equation 2.1 becomes

Maximum applied stress
$$\leq$$
 allowable stress (2.2)

This approach is called *allowable stress design*. The allowable stress will be in the elastic range of the material (see Figure 1.3). This approach to design is also called *elastic design* or *working stress design*. Working stresses are those resulting from the working loads, which are the applied loads. Working loads are also known as *service* loads.

Plastic design is based on a consideration of failure conditions rather than working load conditions. A member is selected by using the criterion that the structure will fail at a load substantially higher than the working load. Failure in this context means either collapse or extremely large deformations. The term *plastic* is used because, at failure, parts of the member will be subjected to very large strainsÑ large enough to put the member into the plastic range (see Figure 1.3b). When the entire cross section becomes plastic at enough locations, •plastic hingesŽwill form at those locations, creating a *collapse mechanism*. As the actual loads will be less than the failure loads by a factor of safety known as the *load factor*, members designed this way are not unsafe, despite being designed based on what happens at failure. This design procedure is roughly as follows.

- 1. Multiply the working loads (service loads) by the load factor to obtain the failure loads.
- 2. Determine the cross-sectional properties needed to resist failure under these loads. (A member with these properties is said to have sufficient strength and would be at the verge of failure when subjected to the factored loads.)
- 3. Select the lightest cross-sectional shape that has these properties.

Members designed by plastic theory would reach the point of failure under the factored loads but are safe under actual working loads.

Load and resistance factor design (LRFD) is similar to plastic design in that strength, or the failure condition, is considered. Load factors are applied to the service loads, and a member is selected that will have enough strength to resist the factored loads. In addition, the theoretical strength of the member is reduced by the application of a resistance factor. The criterion that must be satisfied in the selection of a member is

Factored load
$$\leq$$
 factored strength (2.3)

In this expression, the factored load is actually the sum of all service loads to be resisted by the member, each multiplied by its own load factor. For example, dead loads will have load factors that are different from those for live loads. The factored strength is the theoretical strength multiplied by a resistance factor. Equation 2.3 can therefore be written as

$$(loads \cdot load factors) \le resistance \cdot resistance factor$$
 (2.4)

The factored load is a failure load greater than the total actual service load, so the load factors are usually greater than unity. However, the factored strength is a reduced, usable strength, and the resistance factor is usually less than unity. The factored loads are the loads that bring the structure or member to its limit. In terms of safety, this *limit state* can be fracture, yielding, or buckling, and the factored resistance factor. The limit state can also be one of serviceability, such as a maximum acceptable deflection.