## Numerical Differentiation

Numerical Differentiation is a method used to approximate the value of a derivative over a continuous region [a,b].
Let $f(x)$ is a continuous function with step size $h$. There are forward, backward and centered difference methods to approximate the derivatives of $f(x)$ at a point $x_{i}$.

### 5.1 Forward Difference Approximation of the First Derivative

We know

$$
f^{\prime}(x)=\lim _{\Delta x \rightarrow 0} \frac{f(x+\Delta x)-f(x)}{\Delta x}
$$

For a finite ' $\Delta x$ '.

$$
f^{\prime}(x) \cong \frac{f(x+\Delta x)-f(x)}{\Delta x}
$$



Figure 5.1: Graphical representation of forward difference approximation of first derivative

So if you want to find the value of $f^{\prime}(x)$ at $x=x_{i}$, we may choose another point
' $\Delta x$ ' ahead as $x=x_{i+1}$. This gives
$f^{\prime}\left(x_{i}\right) \cong \frac{f\left(x_{i+1}\right)-f\left(x_{i}\right)}{\Delta x}$

$$
=\frac{f\left(x_{i+1}\right)-f\left(x_{i}\right)}{x_{i+1}-x_{i}} \quad \text { Where } \quad \Delta x=x_{i+1}-x_{i}
$$

## Example 5.1

The velocity of a rocket is given by $v(t)=2000 \ln \left[\frac{14 \times 10^{4}}{14 \times 10^{4}-2100 t}\right]-9.8 t, \quad 0 \leq t \leq 30$ Where ' $v$ ' is given in $\mathrm{m} / \mathrm{s}$ and ' $t$ ' is given in seconds.

Use forward difference approximation of the first derivative of $v(t)$ to calculate the acceleration at $t=16 s$. Use a step size of $\Delta t=2 s$.

## Solution

$$
\begin{aligned}
& a\left(t_{i}\right) \cong \frac{v\left(t_{i+1}\right)-v\left(t_{i}\right)}{\Delta t} \\
& t_{i}=16 \\
& \Delta t=2 \\
& t_{i+1}=t_{i}+\Delta t=16+2=18 \\
& a(16)=\frac{v(18)-v(16)}{2} \\
& v(18)=2000 \ln \left[\frac{14 \times 10^{4}}{14 \times 10^{4}-2100(18)}\right]-9.8(18)=453.02 \mathrm{~m} / \mathrm{s} \\
& v(16)=2000 \ln \left[\frac{14 \times 10^{4}}{14 \times 10^{4}-2100(16)}\right]-9.8(16)=392.07 \mathrm{~m} / \mathrm{s}
\end{aligned}
$$

Hence

$$
a(16)=\frac{v(18)-v(16)}{2}=\frac{453.02-392.07}{2}=30.475 \mathrm{~m} / \mathrm{s}^{2}
$$

The exact value of $a(16)$ can be calculated by differentiating

$$
\begin{aligned}
\mathrm{a}(\mathrm{t}) & =\frac{\mathrm{d}}{\mathrm{dt}}\left[2000 \ln \left[\frac{14 \times 10^{4}}{14 \times 10^{4}-2100 \mathrm{t}}\right]-9.8 \mathrm{t}\right]=2000\left(\frac{14 \times 10^{4}-2100 \mathrm{t}}{14 \times 10^{4}}\right) \frac{\mathrm{d}}{\mathrm{dt}}\left(\frac{14 \times 10^{4}}{14 \times 10^{4}-2100 \mathrm{t}}\right)-9.8 \\
& =2000\left(\frac{14 \times 10^{4}-2100 \mathrm{t}}{14 \times 10^{4}}\right)(-1)\left(\frac{14 \times 10^{4}}{\left(14 \times 10^{4}-2100 \mathrm{t}\right)^{2}}\right)(-2100)-9.8=29.674 \mathrm{~m} / \mathrm{s}^{2}
\end{aligned}
$$

The absolute relative true error is

$$
\left|\epsilon_{t}\right|=\left|\frac{\text { True Value }- \text { App roximate Value }}{\text { True Value }}\right| \times 100=\left|\frac{29.674-30.475}{29.674}\right| \times 100=2.6993 \%
$$

### 5.2 Backward Difference Approximation of the First Derivative

We know

$$
f^{\prime}(x)=\lim _{\Delta x \rightarrow 0} \frac{f(x+\Delta x)-f(x)}{\Delta x}
$$

For a finite ' $\Delta x$ ',

$$
f^{\prime}(x) \cong \frac{f(x+\Delta x)-f(x)}{\Delta x}
$$

If ' $\Delta x$ ' is chosen as a negative number,

$$
\begin{aligned}
& f^{\prime}(x) \cong \frac{f(x+\Delta x)-f(x)}{\Delta x} \\
& f^{\prime}(x)=\frac{f(x)-f(x-\Delta x)}{\Delta x}
\end{aligned}
$$

This is a backward difference approximation as you are taking a point backward from $x$. To find the value of $f^{\prime}(x)$ at $x=x_{i}$, we may choose another point ' $\Delta x^{\prime}$ behind as $x=x_{i-1}$. This gives

$$
f^{\prime}\left(x_{i}\right) \cong \frac{f\left(x_{i}\right)-f\left(x_{i-1}\right)}{\Delta x}
$$

$$
=\frac{f\left(x_{i}\right)-f\left(x_{i-1}\right)}{x_{i}-x_{i-1}} \quad \text { where } \quad \Delta x=x_{i}-x_{i-1}
$$



Figure 5.2 Graphical representation of backward difference approximation of first derivative

## Example 5.2

The velocity of a rocket is given by

$$
v(\mathrm{t})=2000 \ln \left[\frac{14 \times 10^{4}}{14 \times 10^{4}-2100 \mathrm{t}}\right]-9.8 \mathrm{t}, 0 \leq \mathrm{t} \leq 30
$$

Use backward difference approximation of the first derivative of $v(t)$ to calculate the acceleration at $t=16 s$. Use a step size of $\Delta t=2 s$.

## Solution

$$
\begin{aligned}
& a(t) \cong \frac{v\left(t_{i}\right)-v\left(t_{i-1}\right)}{\Delta t} \\
& t_{i}=16 \\
& \Delta t=2 \\
& t_{i-1}=t_{i}-\Delta t=16-2=14 \\
& a(16)=\frac{v(16)-v(14)}{2} \\
& v(16)=2000 \ln \left[\frac{14 \times 10^{4}}{14 \times 10^{4}-2100(16)}\right]-9.8(16)=392.07 \mathrm{~m} / \mathrm{s} \\
& v(14)=2000 \ln \left[\frac{14 \times 10^{4}}{14 \times 10^{4}-2100(14)}\right]-9.8(14)=334.24 \mathrm{~m} / \mathrm{s} \\
& a(16)=\frac{v(16)-v(14)}{2}=\frac{392.07-334.24}{2}=28.915 \mathrm{~m} / \mathrm{s}^{2}
\end{aligned}
$$

The absolute relative true error is

$$
\left|\epsilon_{t}\right|=\left|\frac{29.674-28.915}{29.674}\right| \times 100=2.557 \%
$$

### 5.3 Central Difference Approximation of the First Derivative

As shown above, both forward and backward divided difference approximation of the first derivative are accurate on the order of $0(\Delta x)$. Can we get better approximations?

Yes, another method to approximate the first derivative is called the Central difference approximation of the first derivative.
From Taylor series

$$
\begin{align*}
& f\left(x_{i+1}\right)=f\left(x_{i}\right)+f^{\prime}\left(x_{i}\right) \Delta x+\frac{f^{\prime \prime}\left(x_{i}\right)}{2!}(\Delta x)^{2}+\frac{f^{\prime \prime \prime}\left(x_{i}\right)}{3!}(\Delta x)^{3}+\mathrm{K}  \tag{1}\\
& f\left(x_{i-1}\right)=f\left(x_{i}\right)-f^{\prime}\left(x_{i}\right) \Delta x+\frac{f^{\prime \prime}\left(x_{i}\right)}{2!}(\Delta x)^{2}-\frac{f^{\prime \prime \prime}\left(x_{i}\right)}{3!}(\Delta x)^{3}+\mathrm{K} \tag{2}
\end{align*}
$$

Subtracting equation (2) from equation (1)

$$
\begin{aligned}
& f\left(x_{i+1}\right)-f\left(x_{i-1}\right)=f^{\prime}\left(x_{i}\right)(2 \Delta x)+\frac{2 f^{\prime \prime \prime}\left(x_{i}\right)}{3!}(\Delta x)^{3}+\mathrm{K} \\
& f^{\prime}\left(x_{i}\right)=\frac{f\left(x_{i+1}\right)-f\left(x_{i-1}\right)}{2 \Delta x}-\frac{f^{\prime \prime \prime}\left(x_{i}\right)}{3!}(\Delta x)^{2}+\mathrm{K} \\
& f^{\prime}\left(x_{i}\right)=\frac{f\left(x_{i+1}\right)-f\left(x_{i-1}\right)}{2 \Delta x}+0(\Delta x)^{2} \\
& f^{\prime}\left(x_{i}\right)=\frac{f\left(x_{i+1}\right)-f\left(x_{i-1}\right)}{2 \Delta x}
\end{aligned}
$$

Hence showing that we have obtained a more accurate formula as the error is of the order of $0(\Delta x)^{2}$.


Figure 5.3 Graphical Representation of central difference approximation of first derivative.

## Example 5.3

The velocity of a rocket is given by

$$
v(t)=2000 \ln \left[\frac{14 \times 10^{4}}{14 \times 10^{4}-2100 t}\right]-9.8 t, 0 \leq t \leq 30
$$

Use central divided difference approximation of the first derivative of $v(t)$ to calculate the acceleration at $t=16 \mathrm{~s}$. Use a step size of $\Delta t=2 \mathrm{~s}$.

## Solution

$$
\begin{aligned}
& a\left(t_{i}\right) \cong \frac{v\left(t_{i+1}\right)-v\left(t_{i-1}\right)}{2 \Delta t} \\
& t_{i}=16 \\
& t_{i+1}=t_{i}+\Delta t=16+2=18 \\
& t_{i-1}=t_{i}-\Delta t=16-2=14 \\
& a(16)=\frac{v(18)-v(14)}{2(2)}=\frac{v(18)-v(14)}{4} \\
& v(18)=2000 \ln \left[\frac{14 \times 10^{4}}{14 \times 10^{4}-2100(18)}\right]-9.8(18)=453.02 \mathrm{~m} / \mathrm{s} \\
& v(14)=2000 \ln \left[\frac{14 \times 10^{4}}{14 \times 10^{4}-2100(14)}\right]-9.8(14)=334.24 \mathrm{~m} / \mathrm{s} \\
& a(16)=\frac{v(18)-v(14)}{4}=\frac{453.02-334.24}{4}=29.695 \mathrm{~m} / \mathrm{s}^{2}
\end{aligned}
$$

The absolute relative true error is

$$
\left|\epsilon_{t}\right|=\left|\frac{29.674-29.695}{29.674}\right| \times 100=0.070769 \%
$$

The results from the three difference approximations are given in Table 1.
Table 1 Summary of $a(16)$ using different divided difference approximations.

| Type of Difference <br> Approximation | $a(16)$ <br> $\left(\mathrm{m} / \mathrm{s}^{2}\right)$ | $\left\|\epsilon_{t}\right\| \%$ |
| :---: | :---: | :---: |
| Forward | 30.475 | 2.6993 |
| Backward | 28.915 | 2.557 |
| Central | 29.695 | 0.070769 |

Clearly, the central difference scheme is giving more accurate results because the order of accuracy is proportional to the square of the step size.

### 5.4 Higher Order Derivatives

Example: Second order derivative:
Note that for the centered formulation, it is a derivation of a derivative:
$f^{\prime}(x) \cong \frac{\frac{f\left(x_{i+1}\right)-f\left(x_{i}\right)}{\Delta x}-\frac{f\left(x_{i}\right)-f\left(x_{i-1}\right)}{\Delta x}}{\Delta x}=\frac{f\left(x_{i+1}\right)-2 f\left(x_{i}\right)+f\left(x_{i-1}\right)}{(\Delta x)^{2}}$
Forward

| Backward | $f^{\prime \prime}(x) \cong \frac{f\left(x_{i}\right)-2 f\left(x_{i-1}\right)+f\left(x_{i-2}\right)}{(\Delta x)^{2}}$ |
| :--- | :--- |
| Centered | $f^{\prime \prime}(x) \cong \frac{f\left(x_{i+1}\right)-2 f\left(x_{i}\right)+f\left(x_{i-1}\right)}{(\Delta x)^{2}}$ |

## I) Forward Difference Methods

First Derivative
$f^{\prime}\left(x_{i}\right)=\frac{f\left(x_{i+1}\right)-f\left(x_{i}\right)}{\Delta x}$
Second Derivative

$$
f^{\prime \prime}\left(x_{i}\right)=\frac{f\left(x_{i+2}\right)-2 f\left(x_{i+1}\right)+f\left(x_{i}\right)}{(\Delta x)^{2}}
$$

Third Derivative
$f^{(3)}\left(x_{i}\right)=\frac{f\left(x_{i+3}\right)-3 f\left(x_{i+2}\right)+3 f\left(x_{i+1}\right)-f\left(x_{i}\right)}{(\Delta x)^{3}}$
Fourth Derivative
$f^{(4)}\left(x_{i}\right)=\frac{f\left(x_{i+4}\right)-4 f\left(x_{i+3}\right)+6 f\left(x_{i+2}\right)-4 f\left(x_{i+1}\right)+f\left(x_{i}\right)}{(\Delta x)^{4}}$

## II) Backward Difference Methods

First Derivative
$f^{\prime}\left(x_{i}\right)=\frac{f\left(x_{i}\right)-f\left(x_{i-1}\right)}{\Delta x}$
Second Derivative
$f^{\prime \prime}\left(x_{i}\right)=\frac{f\left(x_{i}\right)-2 f\left(x_{i-1}\right)+f\left(x_{i-2}\right)}{(\Delta x)^{2}}$

Third Derivative

$$
f^{(3)}\left(x_{i}\right)=\frac{f\left(x_{i}\right)-3 f\left(x_{i-1}\right)+3 f\left(x_{i-2}\right)-f\left(x_{i-3}\right)}{(\Delta x)^{3}}
$$

Fourth Derivative

$$
f^{(4)}\left(x_{i}\right)=\frac{f\left(x_{i}\right)-4 f\left(x_{i-1}\right)+6 f\left(x_{i-2}\right)-4 f\left(x_{i-3}\right)+f\left(x_{i-4}\right)}{(\Delta x)^{4}}
$$

## III) Central Difference Methods

First Derivative

$$
f^{\prime}\left(x_{i}\right)=\frac{f\left(x_{i+1}\right)-f\left(x_{i-1}\right)}{2 \Delta x}
$$

Second Derivative

$$
f^{\prime \prime}\left(x_{i}\right)=\frac{f\left(x_{i+1}\right)-2 f\left(x_{i}\right)+f\left(x_{i-1}\right)}{(\Delta x)^{2}}
$$

Third Derivative

$$
f^{(3)}\left(x_{i}\right)=\frac{f\left(x_{i+2}\right)-2 f\left(x_{i+1}\right)+2 f\left(x_{i-1}\right)-f\left(x_{i-2}\right)}{2(\Delta x)^{3}}
$$

Fourth Derivative

$$
f^{(4)}\left(x_{i}\right)=\frac{f\left(x_{i+2}\right)-4 f\left(x_{i+1}\right)+6 f\left(x_{i}\right)-4 f\left(x_{i-1}\right)+f\left(x_{i-2}\right)}{(\Delta x)^{4}}
$$

