

* Example (1)

The weights of four masses $W_1, W_2, W_3,$ and W_4 are (200 kg), (300 kg), (240 kg) and (260 kg) respectively. The corresponding radii of rotation are (20 cm), (15 cm), (25 cm) and (30 cm) respectively, and the angles between these masses are (45°), (75°) and (135°). Find the position and magnitude of the balancing weight required, if its radius of rotation is (20 cm), and all masses in the same plane.

* Solution:

1- Table the given data:

Weights	mass (kg)	radius (cm)	angles (deg)	W r kg cm
W_1	200	20	0°	4000
W_2	300	15	45°	4500
W_3	240	25	$\theta_3 = 45^\circ + 75^\circ = 120^\circ$	6000
W_4	260	30	$\theta = 45^\circ + 75^\circ + 135^\circ = 255^\circ$	7800
W_b	=?	20	$\theta_b = ?$	$20 W_b$

2- As shown in Fig (a)

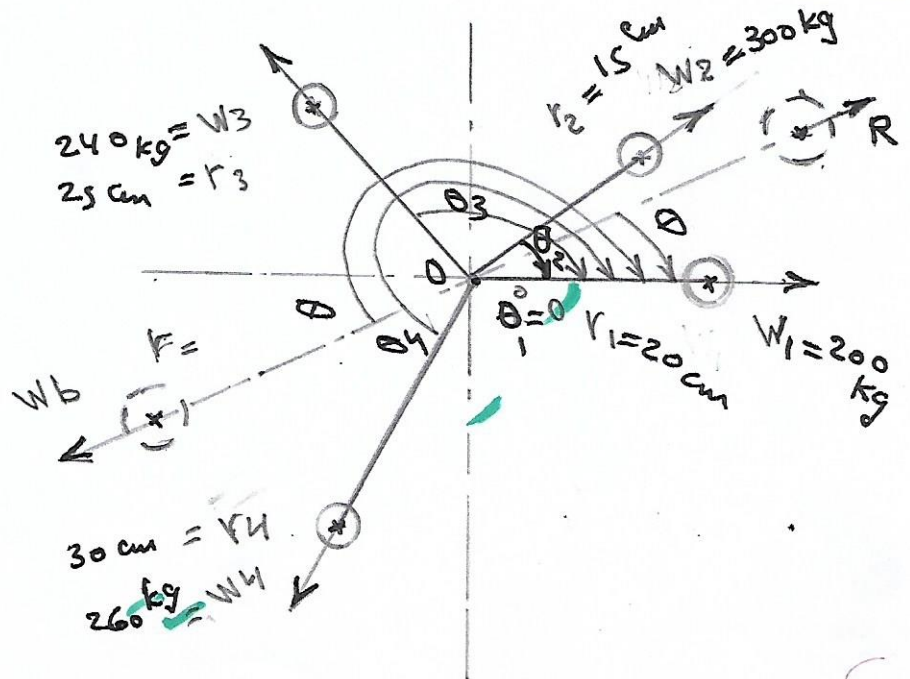


Fig (a)

The magnitude and position (direction) of the balancing weight may be found by two ways:

1) Analytical Method:

الطريق التحليلي

is done by resolving the centrifugal forces horizontally and vertically, and find their resultant, as follow:

$$\begin{cases} \sum R_H = W_1 r_1 \cos \theta_1 + W_2 r_2 \cos \theta_2 + W_3 r_3 \cos \theta_3 + W_4 r_4 \cos \theta_4 \\ \sum R_V = W_1 r_1 \sin \theta_1 + W_2 r_2 \sin \theta_2 + W_3 r_3 \sin \theta_3 + W_4 r_4 \sin \theta_4 \end{cases}$$

$$\therefore \begin{cases} \sum R_H = 200 \times 20 \times \cos 0^\circ + 300 \times 15 \times \cos 45^\circ + 240 \times 25 \times \cos 120^\circ + 260 \times 30 \times \cos 255^\circ \\ = 2122 \text{ kg} \cdot \text{cm} \end{cases}$$

$$\begin{cases} \sum R_V = 200 \times 20 \sin 0^\circ + 300 \times 15 \times \sin 45^\circ + 240 \times 25 \times \sin 120^\circ + 260 \times 30 \times \sin 255^\circ \\ = 2862.7 \\ = 811 \text{ kg} \cdot \text{cm} \end{cases}$$

∴ The resultant c. force.

$$R = \sqrt{(\sum R_H)^2 + (\sum R_V)^2} = \sqrt{(2122)^2 + (811)^2} = 2200 \text{ kg} \cdot \text{cm}$$

But we know that

$$R = W \times r = 2200 \text{ kg} \cdot \text{cm}$$

$$\therefore W = \frac{R}{r} = \frac{2200}{20} = 110 \text{ kg} \rightarrow \text{balance weight}$$

$$\text{and } \tan \theta = \frac{\sum V}{\sum H} = \frac{811}{2122} = 0.384$$

$$\therefore \theta_R = 21^\circ$$

Force → position of resultant

∴ $\theta_B = 180 + 21 = 201^\circ$ → Position of balancing weight - which is equal and opposite direction of resultant

$$W_B = \leftarrow R$$

*2- Graphical Method

الطريقة البيانية

The magnitude and position of balancing weight may be found as follow:

*I, Draw space diagram for all masses and their positions, with suitable scale

$\therefore W_1 r_1 = 200 \times 20 = 4000 \text{ kg.cm}$

$W_2 r_2 = 300 \times 15 = 4500 \text{ kg.cm}$

$W_3 r_3 = 240 \times 25 = 6000 \text{ kg.cm}$

$W_4 r_4 = 260 \times 30 = 7800 \text{ kg.cm}$

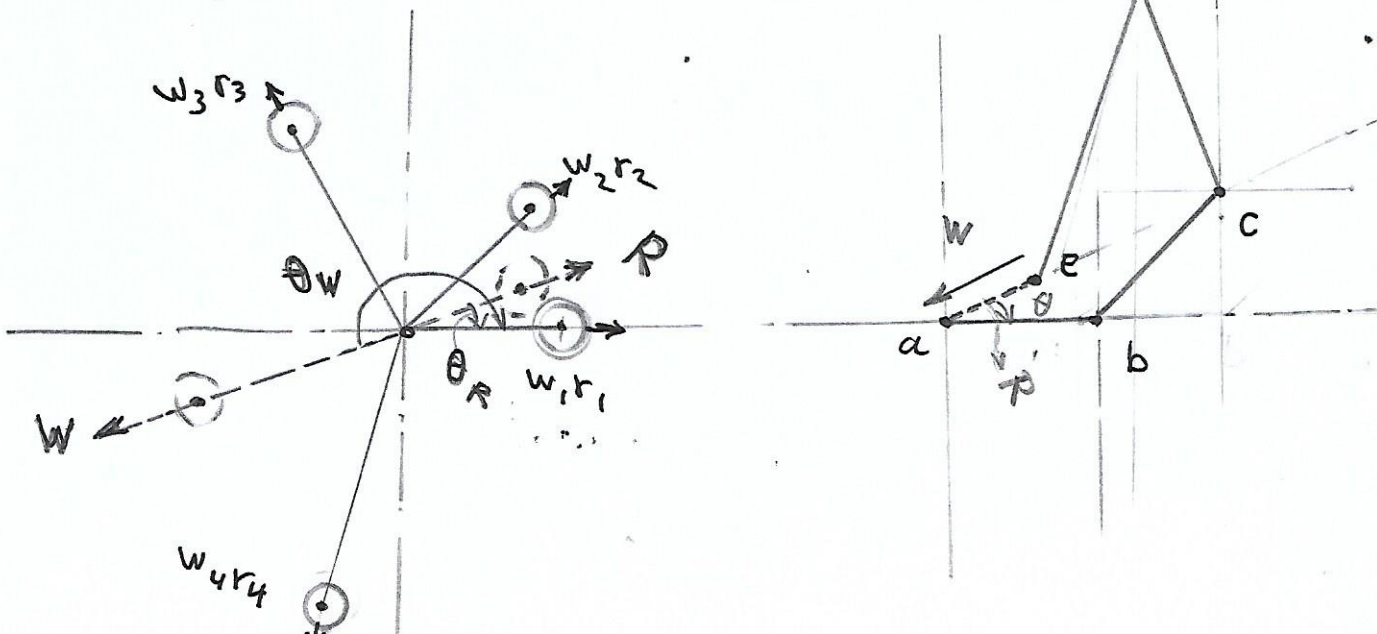
Take Scal: 1000 kg.cm = 5 mm

$\therefore k_e = \frac{W_1 r_1}{W_1 r_1} = \frac{W_1 r_1 \times \frac{5}{1000}}{4000 \times \frac{5}{1000}} = 200$

$\therefore \frac{W_1 r_1}{k_e} = \frac{4000}{200} = 20 \text{ mm}$

$\frac{W_2 r_2}{k_e} = \frac{4500}{200} = 22.5 \text{ mm}$

$\frac{W_3 r_3}{k_e} = \frac{6000}{200} = 30 \text{ mm}$



- 7 -

III) Take pol (a), and from a draw all the vector $w, r_1 = 20 \text{ mm}$ length, and with angle $\theta = 0$, ---

then from vector diagram measure

$$W \cdot r = \bar{a}e = 11 \text{ mm} * k_l = 11 * 200 = 2200 \text{ kg} \cdot \text{cm}$$

$$\therefore W = \frac{2200}{r} = \frac{2200}{20} = \boxed{110 \text{ kg}} \rightarrow \text{balancing weight}$$

also we measure angle θ between $\bar{a}e$ and $\bar{a}b$

$\therefore \theta_R = 21^\circ \rightarrow$ angle of inclination of R-force

\therefore inclination of balancing weight = and opposite direction.

$$\theta_w = 180^\circ + 21^\circ = 201^\circ$$

* example(2):

A shaft carries four rotating masses A, B, C and D in this order along its axis. The mass A may be assumed to be concentrated at radius of (18 cm), B at (24 cm), C at (12 cm), and D at (15 cm). The weights of B, C and D are (30 kg), (50 kg), and (40 kg) respectively. The planes containing B, C and D are (30 cm) apart. The angular spacing of the planes containing C and B are (90°) and (210°) respectively relative to B measured in the same sense. If the shaft and masses are to be in complete dynamic balance: Find:

- 1- The weight and angular position of mass A,
- 2- The position of the planes A and D.

Solution:

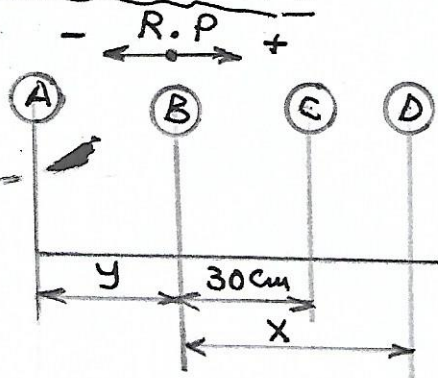


Fig (a)

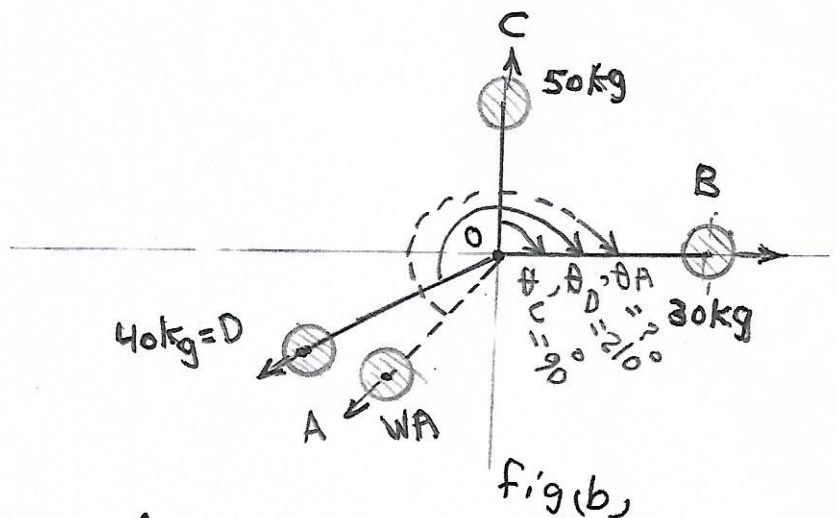


Fig (b)

- 1) Assume; plane B a reference plane.
- X - distance between plane D and B
 - Y - distance between plane A and B
 - W_A - weight of mass A
 - $\theta_A = \angle AOB$ - angular position of mass A as shown in fig (a) and fig (b)

2) Tabulate the given data as follow:

Plane -1	Weight W (kg) 2	radius r (cm) 3	Centrifugal force $\frac{w^2}{g}$ W.r (kg.cm) 4	Distance from Plane B L (cm) 5	Couple $\frac{w^2}{g}$ W.r.L (kg.cm ²) 6
A	W _A	18	18 W _A	-y	-18 W _A · y
B (R-P)	300	24	720	0	0
C	50	12	600	30	18000
D	40	15	600	+X	600X

3- The weight of mass A may be determine by drawing the force polygon from Column (4) of the table, with suitable scale as shown in fig (c)

I, assume scale 20 kg/cm = 1 mm or 1 kg.cm = 20 mm

$$\therefore k_f = \frac{W_B \cdot r_B}{W_B \cdot r_B} = \frac{720}{720 \times \frac{1}{20}} = \frac{720}{36} = \boxed{20}$$

II, Take pole O, and from O draw vector ob // and = to = 36 mm, by same way draw other forces as shown in fig (c) where F_c = 30 mm, F_d = 30 mm, F_A = ?

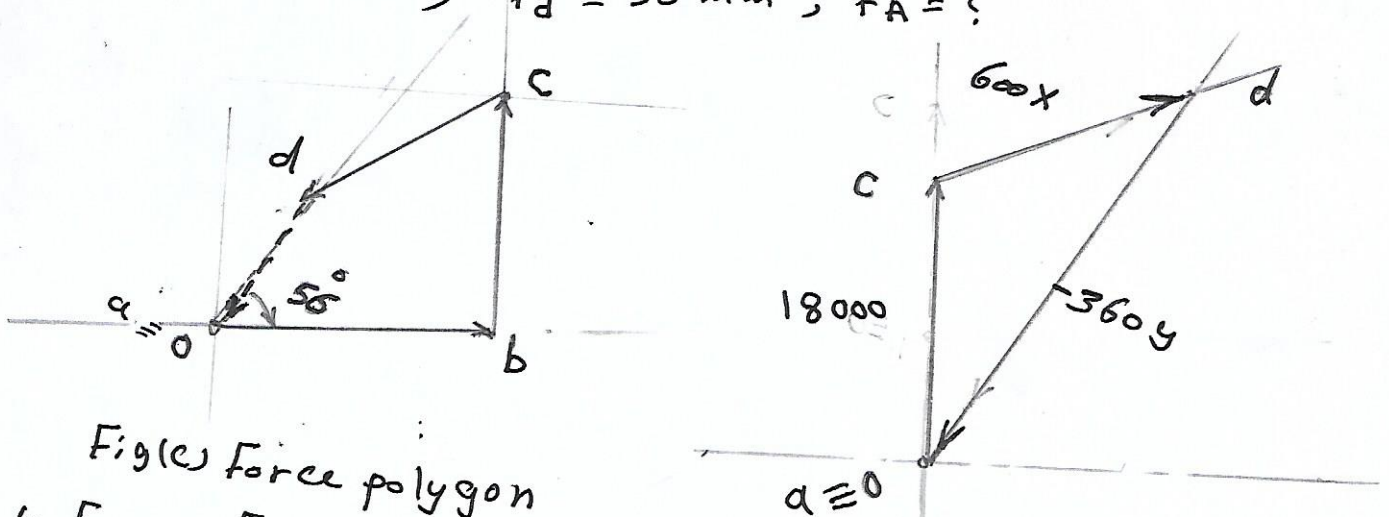


Fig (c) Force polygon

∴ From Fig (c) we get

The closing side do = W_A r_A = 18 W_A = 18 mm * k_f = 18 * 20

$$\therefore W_A = \frac{18 \times 20}{18} = \boxed{20 \text{ kg}}$$

2 - By measuring the angle between vectors od and ob we get $\angle do b = 56^\circ$
 $\therefore \theta_A = 180 + 56 = \boxed{236^\circ}$

4 - Position of plane A, D may be determined by drawing Couple Polygon with suitable scale from Column (6) as follow.

I, assume scale for couple $600 \text{ kg, cm}^2 = 1 \text{ mm}$
 $\therefore k_{\text{couple}} = \frac{w_c t_2 \cdot l_c}{w_c \cdot r_c \cdot l_c} = \frac{18000}{18000 \times \frac{1}{600}} = \frac{18000}{30} = \boxed{600}$

II, Take pole o , and from o draw Couple $OC = 30 \text{ mm}$
 and oe , and from o draw od

From c draw $\parallel od$ measur
 From o draw $\parallel oa$ $\times d$ measur
 $cd = 37.5 \text{ mm} \times k_c$
 $od = 58.75 \text{ mm} \times k_c$

$\therefore 600 \times x = cd = 37.5 \times 600 = 22500 \text{ kg, cm}^2$
 $\therefore x = \frac{22500}{600} = 37.5 \text{ cm}$

and $18 \times 20 \times y = da = 58.75 \times 600 = 35250 \text{ kg, cm}^2$
 $\therefore y = \frac{35250}{18 \times 20} = 97.9 \text{ cm, to the left of R-plane.}$

Example (3) :

A shaft is supported in bearings (180 cm) apart and projects (45 cm) beyond bearings at each end. The shaft carries three pulleys one at each end and one at the middle of the length. The end pulleys weight (48 kg) and (20 kg), and their centre of gravity are (1.5 cm) and (1.25 cm) respectively from the shaft axis. The centre pulley weights (56 kg) and its centre of gravity is (1.5 cm) from the shaft axis. If the pulleys are arranged so as to give static balance. Determine a) relative angular positions of the pulleys, and b) dynamic forces produced on the bearings when the shaft rotates at ($n=300 \text{ r.p.m}$).

Solution:

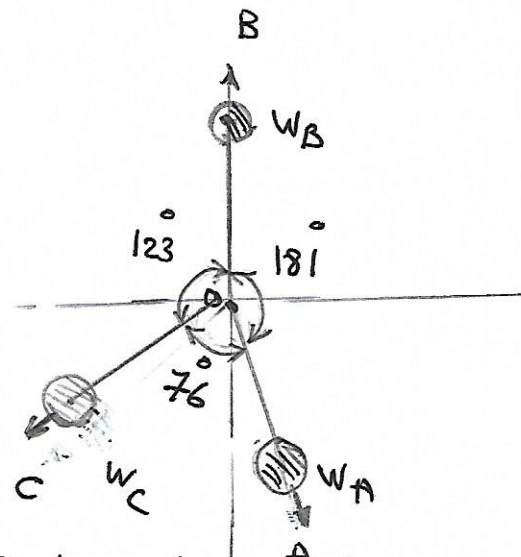
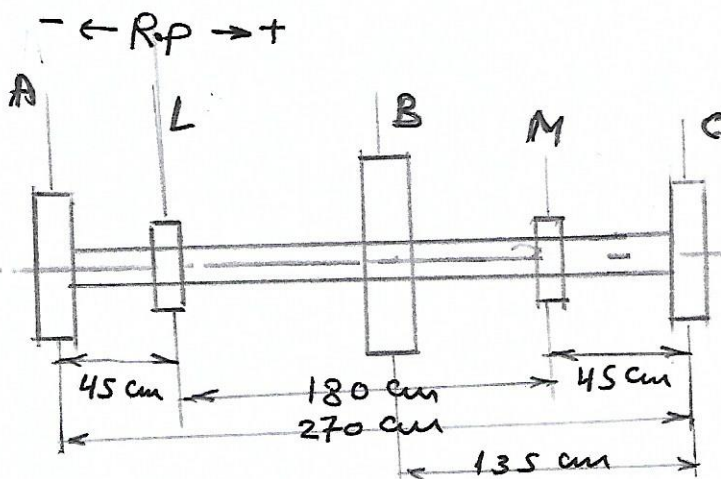


Fig (b) angular position

Fig (a) show the position of shaft and pulleys

1- Take plane L - R - P.

2) Tabulate the given data as follows:

plans	Weight (W) kg	radius (r cm)	Cent-force = w^2/g (W.r) kg.cm	Distance from P-L (L) cm	Couple = $w \cdot r$ (W.r.L) kg.cm ²	angles (θ°)
(1) A	48	1.5	72	-45	-3246	
L (R.P)	WL	rl	WlrL	0	0	
B	56	1.5	84	90	7560	
M	WM	rM	WMrM	180	180WMrM	
C	20	1.25	25	225	5625	

a) For determining the angular position of the pulleys take the system in static balance, as shown in fig (a), and assume the weight W_B is vertical.

Then draw force polygon with suitable scale: assume $2.5 \text{ kg} = 1 \text{ mm}$ from column (4)

$$\therefore k_{FW} = \frac{W_C \cdot r}{W_C \cdot r \times \frac{1}{2.5}} = \frac{25}{25 \times \frac{1}{2.5}} = \frac{25}{10} = \boxed{2.5}$$

\therefore Take pole O and draw $Oa = 10 \text{ mm}$ and in same direction, so the other forces by same way.
 $\therefore W_C \cdot r = 10 \text{ mm}$, $W_A \cdot r = 28.8 \text{ mm}$, $W_B \cdot r = 33.6 \text{ mm}$

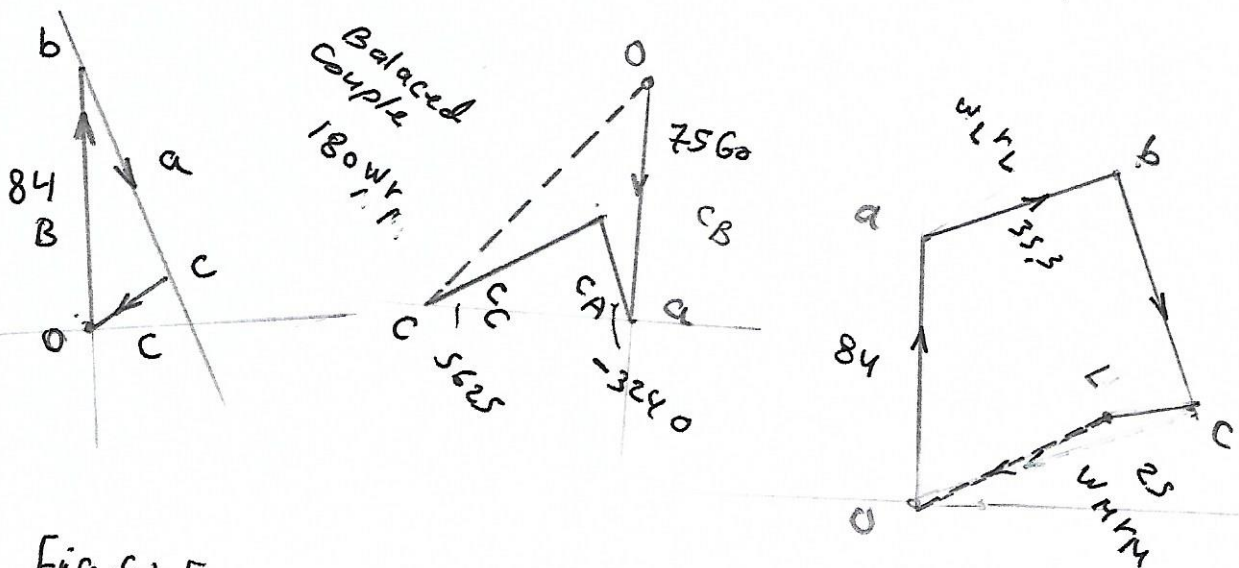


Fig (c) F₂ polygon.

From fig(c) we get

$$\theta A \circ B = 161^\circ$$

$$\theta C \circ B = 75^\circ$$

b - for determining the dynamic forces on bearings (reactions), draw the couple polygon from Column (6), with suitable scale.

where

$$\begin{cases} \text{Couple A} = -3240 \\ \text{Couple B} = +7560 \\ \text{Couple C} = +5625 \end{cases}$$

\therefore Take scale for Couple $224 \text{ kg} \cdot \text{m} = 1 \text{ m}$

$$\therefore k_{\text{couple}} = \frac{\text{Couple B}}{\text{Couple B} \times \frac{1}{224}} = \frac{7560}{7560 \times \frac{1}{224}} = \frac{7560}{33,8} = \boxed{224}$$

\therefore Take pole o and draw $CB = 33,8 \text{ mm} \parallel oA$, and the other couples by same way, as in fig(d),
 $CA = 14,5 \text{ mm}$, $Cc = 23 \text{ mm}$

\therefore The balanced couple at bearing M

$$180 \text{ W}_L r_L = 9710 \text{ kg} \cdot \text{cm}$$

$$\therefore \text{W}_L r_L = 53,3 \text{ kg} \cdot \text{cm} = \text{W}_M r_M = 53,3 \text{ kg} \cdot \text{cm} = F_B$$

Dynamic force at bearing L

$$F_c = \frac{W_L}{g} \times \omega^2 r_L = \frac{W_L r_L}{g} \left(\frac{2\pi n}{60} \right)^2 = \frac{53,3}{981} \times \left(\frac{2 \times 3,14 \times 300}{60} \right)^2$$

$$= 54,34 \text{ kg} \rightarrow \text{dynamic force on bearing L}$$

* For determining the dynamic force on bearing (M)
 draw force polygon from Column (4)

Take scale

with suitable scale:
 Take scale 2,4 kg, cm = 1 mm

$$\therefore k_{fc} = \frac{F_{cB}}{f_{cB} \cdot \frac{1}{2,4}} = \frac{84}{84 \times \frac{1}{2,4}} = \frac{84}{35} = \boxed{2,4}$$

\therefore Take pole o and from o draw $f_{cB} = 35$ mm // WB , then the other force draw by same way as shown in figure,

\therefore Dynamic force a bearing M

$$\frac{W_M}{g} \omega_{rm}^2 = \frac{W_M r_m}{g} \left(\frac{2\pi n}{60} \right)^2$$

$$= \frac{53.3}{981} \left(\frac{2 \times 3,14 \times 300}{60} \right)^2 = 54.34 \text{ kg} \rightarrow \text{dynamic force on bearing } M$$