

AL- MUSTAQBAL UNIVERSITY COLLEGE DEPARTMENT OF BIOMEDICAL ENGINEERING

Signals and Systems for BME BME 322

Lecture 6

- Infinite Impulse Response (IIR) Filters -

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Infinite Impulse Response (IIR) Filters

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- IIR filters are recursive filters.
- Difference equation for IIR filters

$$y[n] = -\sum_{K=1}^{N} a_k y[n-k] + \sum_{K=0}^{M} b_k x[n-k]$$

 a_k and b_k are the filter coefficients

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• IIR filters outputs depends on N past outputs and M past inputs.

• The impulse response samples getting smaller and smaller but they never settle to zero.





Determine the first three samples in the impulse response for the IIR filter.

$$y[n] - 0.2 y[n-1] = x[n] + x[n-1]$$

Sol:

Substituting $\delta[n]$ for x[n] and h[n] for y[n].

$$h[n] - 0.2 h[n-1] = \delta[n] + \delta[n-1]$$

$$h[n] = 0.2 h[n-1] + \delta[n] + \delta[n-1]$$

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= 0.2(1) + 0.0 + 1.0 = 1.2

 $h[0] = 0.2 h[-1] + \delta[0] + \delta[-1]$

 $h[0] = 0.2 h [0-1] + \delta [0] + \delta [0-1]$

= 0.0 + 1.0 + 0.0 = 1.0

 $h[1] = 0.2 h [1-1] + \delta [1] + \delta [1-1]$

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 $h[2] = 0.2 h [2-1] + \delta [2] + \delta [2-1]$

= 0.2 (1.2) + 0.0 + 0.0 = 0.24

 $h[3] = 0.2 h [3-1] + \delta [3] + \delta [3-1]$

= 0.2 (0.24) + 0.0 + 0.0 = 0.048





Determine the first four samples in the impulse response for the IIR filter.

$$y[n] - 0.4 y[n-1] = x[n] - x[n-1]$$

Sol:

Substituting $\delta[n]$ for x[n] and h[n] for y[n].

$$h[n] - 0.4 h[n-1] = \delta[n] - \delta[n-1]$$

$$h[n] = 0.4 h[n-1] + \delta[n] - \delta[n-1]$$





$$h [0] = 0.4h [-1] + \delta [0] - \delta [n - 1]$$
$$= 0.4 (0.0) + 1.0 - 0.0 = 1.0$$
$$h [1] = 0.4h [0] + \delta [1] - \delta [0]$$
$$= 0.4 (1.0) + 0.0 - 1.0 = -0.6$$
$$h [2] = 0.4h [1] + \delta [2] - \delta [1]$$
$$= 0.4 (-0.6) + 0.0 - 0.0 = -0.24$$





 $h[3] = 0.4h[2] + \delta[3] - \delta[2]$

= 0.4 (-0.24) + 0.0 - 0.0 = -0.096

 $h [4] = 0.4h [3] + \delta [4] - \delta [3]$

= 0.4 (-0.96) + 0.0 - 0.0 = -0.0384

 $h[5] = 0.4h[4] + \delta[5] - \delta[4]$

= 0.4 (-0.0384) + 0.0 - 0.0 = -0.01536

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