



Biomedical Engineering
Engineering Analysis
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Lecture (8)

Matrices

1. Linearly Dependent & Linearly Independent Vectors

The vectors $V_1, V_2, V_3, \dots, V_m$ are linearly dependent if and only if $|V_1 \ V_2 \ V_3 \ \dots \ V_m| = 0$. If $|V_1 \ V_2 \ V_3 \ \dots \ V_m| \neq 0$ then $V_1, V_2, V_3, \dots, V_m$ are linearly independent.

Example 1

$$V_1 = (3, 6, -1), V_2 = (8, 2, -4), V_3 = (1, -1, 1)$$

$$\text{Since } \begin{vmatrix} 3 & 8 & 1 \\ 6 & 2 & -1 \\ -1 & -4 & 1 \end{vmatrix} = 3 \begin{vmatrix} 2 & -1 \\ -4 & 1 \end{vmatrix} - 8 \begin{vmatrix} 6 & -1 \\ -1 & 1 \end{vmatrix} + 1 \begin{vmatrix} 6 & 2 \\ -1 & -4 \end{vmatrix}$$

$$3(2 - 4) - 8(6 - 1) + (-24 + 2) = -6 - 40 - 22 = -68 \neq 0$$

Then V_1, V_2, V_3 are linearly independent

$$V_1 = (2, 4, 6), V_2 = (1, 3, 3), V_3 = (1, 2, 3)$$

$$\text{Since } \begin{vmatrix} 2 & 1 & 1 \\ 4 & 3 & 2 \\ 6 & 3 & 3 \end{vmatrix} = 2 \begin{vmatrix} 3 & 2 \\ 3 & 3 \end{vmatrix} - 1 \begin{vmatrix} 4 & 2 \\ 6 & 3 \end{vmatrix} + 1 \begin{vmatrix} 4 & 3 \\ 6 & 3 \end{vmatrix}$$

$$= 2(9 - 6) - (12 - 12) + (12 - 18) = 6 - 0 - 6 = 0$$

Then V_1, V_2, V_3 are linearly dependent

2. Linearly Dependent & Linearly Independent Functions

If $y_1, y_2, y_3, \dots, y_m$ are functions of x then $y_1, y_2, y_3, \dots, y_m$ are linearly dependent if $w(y_1, y_2, y_3, \dots, y_m) = 0$ where

$$w(y_1, y_2, y_3, \dots, y_m) = \begin{vmatrix} y_1 & y_2 & \dots & y_m \\ y'_1 & y'_2 & \dots & y'_m \\ y_1^{(m-1)} & y_2^{(m-1)} & \dots & y_m^{(m-1)} \end{vmatrix}$$

If $w(y_1, y_2, y_3, \dots, y_m) \neq 0$ then $y_1, y_2, y_3, \dots, y_m$ are linearly independent

Example: 1) $y_1 = e^x, y_2 = x^2$

$$w(y_1, y_2) = \begin{vmatrix} e^x & x^2 \\ e^x & 2x \end{vmatrix} = 2xe^x - x^2e^x = xe^x(2-x) \neq 0$$

So y_1 and y_2 are linearly independent

2) $y_1 = 4e^x, y_2 = 2e^x$

$$w(y_1, y_2) = \begin{vmatrix} 4e^x & 2e^x \\ 4e^x & 2e^x \end{vmatrix} = 8e^{2x} - 8e^{2x} = 0 \quad \text{So } y_1 \text{ and } y_2 \text{ are linearly dependent}$$

Gauss Elimination Method

The system of linear equations is denoted by

$AX = B$ where A is a matrix, X and B are vectors

This system is solved by using the Gauss elimination method as shown below.

Example:

The system

$$x_1 - 2x_2 = 3$$

$$4x_1 + 6x_2 = 5$$

Can be written as

$$\begin{bmatrix} 1 & -2 \\ 4 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$$

So, by using the Gauss elimination method as follows:

$$\left[\begin{array}{cc|c} 1 & -2 & 3 \\ 4 & 6 & 5 \end{array} \right]$$

$$4R_1 - R_2 \rightarrow \left[\begin{array}{cc|c} 1 & -2 & 3 \\ 0 & -14 & 7 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 1 & -2 & 3 \\ 0 & -14 & 7 \end{array} \right] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 7 \end{bmatrix} \rightarrow x_1 - 2x_2 = 3, -14x_2 = 7$$

$$-14x_2 = 7 \rightarrow x_2 = -\frac{1}{2} \rightarrow x_1 = 2\left(-\frac{1}{2}\right) + 3 = 2$$

The solution is $\begin{bmatrix} 2 \\ -1/2 \end{bmatrix}$

Matrix Inverse

We can use the Gauss elimination method to find the inverse of a matrix, we know that a matrix A and its inverse A^{-1} must satisfy the equation $A \times A^{-1} = I$ (identity matrix). The following example illustrates the procedure.

Example: Find A^{-1} if

$$A = \begin{bmatrix} 2 & 1 \\ 1 & 4 \end{bmatrix}$$

Solution

$$\left[\begin{array}{cc|cc} 2 & 1 & 1 & 0 \\ 1 & 4 & 0 & 1 \end{array} \right] \rightarrow \frac{1}{2}R_1 \rightarrow \left[\begin{array}{cc|cc} 1 & 1/2 & 1/2 & 0 \\ 1 & 4 & 0 & 1 \end{array} \right]$$

$$R_2 - R_1 \rightarrow \left[\begin{array}{cc|cc} 1 & 1/2 & 1/2 & 0 \\ 0 & 7/2 & -1/2 & 1 \end{array} \right] \rightarrow \frac{2}{7}R_2 \rightarrow \left[\begin{array}{cc|cc} 1 & 1/2 & 1/2 & 0 \\ 0 & 1 & -1/7 & 2/7 \end{array} \right]$$

$$R_1 - \frac{1}{2}R_2 \rightarrow \left[\begin{array}{cc|cc} 1 & 0 & \frac{4}{7} & -\frac{1}{7} \\ 0 & 1 & -\frac{1}{7} & \frac{2}{7} \end{array} \right] \rightarrow A^{-1} = \begin{bmatrix} 4/7 & -1/7 \\ -1/7 & 2/7 \end{bmatrix}$$

Note: The matrix A has an inverse if $|A| \neq 0$

Eigen Values & Eigen Vectors

Let A be an $n \times n$ matrix, a real or complex number λ is called an Eigen value of A if $\det(A - \lambda I) = 0$ and with $[A - \lambda I]x = 0$ then x is called an Eigen vector with respect to λ where I is the identity matrix.

Example: Find the Eigen values and Eigen vectors of A if

a) $A = \begin{bmatrix} 1 & 2 \\ -1 & -2 \end{bmatrix}$, b) $A = \begin{bmatrix} 1 & 3 \\ 2 & 1 \end{bmatrix}$, c) $A = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & -1 \end{bmatrix}$

Sol.: a) To find Eigen values, we have $\det(A - \lambda I) = 0$ then

$$A - \lambda I = \begin{vmatrix} 1 - \lambda & 2 \\ -1 & -2 - \lambda \end{vmatrix} = 0 \rightarrow (1 - \lambda)(-2 - \lambda) + 2 = 0 \rightarrow -2 - \lambda + 2\lambda + \lambda^2 + 2 = 0$$

$$\rightarrow \lambda^2 + \lambda = 0 \rightarrow \lambda(\lambda + 1) = 0 \rightarrow \lambda_1 = 0, \lambda_2 = -1$$

To find the Eigen vectors, we have $[A - \lambda I]X = 0$

$$\text{For } \lambda_1 = 0 \rightarrow \begin{bmatrix} 1 & 2 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0$$

$$x_1 + 2x_2 = 0 \rightarrow x_1 = -2x_2$$

Let $x_2 = 1 \rightarrow x_1 = -2 \rightarrow \text{The Eigen vector for } \lambda_1 = 0 \text{ is } \begin{bmatrix} -2 \\ 1 \end{bmatrix}$

$$\text{For } \lambda_2 = -1 \rightarrow \begin{bmatrix} 2 & 2 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0$$

$$2x_1 + 2x_2 = 0 \rightarrow 2x_1 = -2x_2 \rightarrow x_1 = -x_2$$

Let $x_2 = 1 \rightarrow x_1 = -1 \rightarrow$ The Eigen vector for $\lambda_2 = -1$ is $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$

b) To find Eigen values, we have $\det(A - \lambda I) = 0$ then

$$\begin{aligned} A - \lambda I &= \begin{vmatrix} 1 - \lambda & 3 \\ 2 & 1 - \lambda \end{vmatrix} = 0 \rightarrow (1 - \lambda)^2 - 6 = 0 \rightarrow 1 - 2\lambda + \lambda^2 - 6 = 0 \\ &\rightarrow \lambda^2 - 2\lambda - 5 = 0 \rightarrow \frac{-B \pm \sqrt{B^2 - 4AC}}{2A} = \frac{+2 \pm \sqrt{4 + 20}}{2} = 1 \pm \sqrt{6} \end{aligned}$$

$$\lambda_1 = 1 + \sqrt{6}, \lambda_2 = 1 - \sqrt{6}$$

To find the Eigen vectors, we have $[A - \lambda I]X = 0$

$$\text{For } \lambda_1 = 1 + \sqrt{6} \rightarrow \begin{bmatrix} -\sqrt{6} & 3 \\ 2 & -\sqrt{6} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0$$

$$-\sqrt{6}x_1 + 3x_2 = 0 \rightarrow -\sqrt{6}x_1 = -3x_2 \rightarrow x_1 = \frac{3}{\sqrt{6}}x_2$$

$$\text{Let } x_2 = 1 \rightarrow x_1 = \frac{3}{\sqrt{6}} \rightarrow \text{The Eigen vector for } \lambda_1 = 1 + \sqrt{6} \text{ is } \begin{bmatrix} \frac{3}{\sqrt{6}} \\ 1 \end{bmatrix}$$

$$\text{For } \lambda_2 = 1 - \sqrt{6} \rightarrow \begin{bmatrix} \sqrt{6} & 3 \\ 2 & \sqrt{6} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0$$

$$\sqrt{6}x_1 + 3x_2 = 0 \rightarrow \sqrt{6}x_1 = -3x_2 \rightarrow x_1 = \frac{-3}{\sqrt{6}}x_2$$

$$\text{Let } x_2 = 1 \rightarrow x_1 = \frac{-3}{\sqrt{6}} \rightarrow \text{The Eigen vector for } \lambda_2 = 1 - \sqrt{6} \text{ is } \begin{bmatrix} \frac{-3}{\sqrt{6}} \\ 1 \end{bmatrix}$$

c) To find Eigen values, we have $\det(A - \lambda I) = 0$ then

$$A - \lambda I = \begin{vmatrix} 1 - \lambda & -1 & 0 \\ 0 & 1 - \lambda & 1 \\ 0 & 0 & -1 - \lambda \end{vmatrix} = 0 \rightarrow (1 - \lambda) \begin{vmatrix} 1 - \lambda & 1 \\ 0 & -1 - \lambda \end{vmatrix} + 1 \begin{vmatrix} 0 & 1 \\ 0 & -1 - \lambda \end{vmatrix} = 0$$

$$\rightarrow -(1 - \lambda)^2(1 + \lambda) = 0 \rightarrow -(1 - 2\lambda + \lambda^2)(1 + \lambda) \rightarrow -((\lambda - 1)(\lambda + 1))(\lambda - 1) = 0$$

$$-\lambda_1 + 1 = 0 \rightarrow \lambda_1 = 1, -\lambda_2 + 1 = 0 \rightarrow \lambda_2 = 1, -1 - \lambda_3 = 0 \rightarrow \lambda_3 = -1$$

$$\rightarrow \lambda_1 = 1, \lambda_2 = 1, \text{ and } \lambda_3 = -1$$

To find the Eigen vectors, we have $[A - \lambda I]X = 0$

$$\text{For } \lambda_{1,2} = 1 \rightarrow \begin{vmatrix} 0 & -1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & -2 \end{vmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0, -x_2 = 0, x_3 = 0, -2x_3 = 0$$

$$\text{The Eigen vector for } \lambda_{1,2} = 1 \text{ is } \begin{bmatrix} a \\ 0 \\ 0 \end{bmatrix}$$

Each choice of a gives us an Eigen vector associated with $\lambda = 1$

$$\text{For } \lambda_3 = -1 \rightarrow \begin{bmatrix} 2 & -1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$$2x_1 - x_2 = 0 \rightarrow 2x_1 = x_2 \rightarrow 2x_2 + x_3 = 0 \rightarrow 2x_2 = -x_3$$

$$\text{Let } x_1 = 1 \rightarrow x_2 = 2 \rightarrow x_3 = -4$$

The Eigen vector for $\lambda_3 = -1$ is $\begin{bmatrix} 1 \\ 2 \\ -4 \end{bmatrix}$

ملاحظات عن الكسور الجزئية

(Partial Fraction)

الكسور الجزئية هي عملية عكسية لتوحيد المقامات وشروطها

١. درجة البسط اقل من درجة المقام او تساويها
٢. توزيع المقام
٣. نفرض قيمة لل x مناسبة لتصفير احد المتغيرات لايجاد المتغير الآخر او الحل بطريقة المعادلات.

حل مثال ١٣ في محاضرة ٦ بالتفصيل

Example 13. Solve the equation $\frac{d^2x}{dt^2} - 3 \frac{dx}{dt} + 2x = 2e^{3t}$ given that $t = 0, x = 5, \frac{dx}{dt} = 7$

$$\text{Sol: .} (s^2 x' - sx_0 - x_1) - 3(s x' - x_0) + 2 x' = \frac{2}{s-3}$$

$$s^2 x' - 5s - 7 - 3sx' + 15 + 2 x' = \frac{2}{s-3}$$

$$x'(s^2 - 3s + 2) - 5s + 8 = \frac{2}{s-3}$$

$$x'(s-1)(s-2) = \frac{2}{s-3} + 5s - 8$$

$$x'(s-1)(s-2) = \frac{2 + 5s(s-3) - 8(s-3)}{s-3}$$

$$x' = \frac{5s^2 - 23s + 26}{(s-3)(s-1)(s-2)}$$

$$\frac{5s^2 - 23s + 26}{(s-1)(s-2)(s-3)} = \frac{A}{s-1} + \frac{B}{s-2} + \frac{C}{s-3}$$

$$5s^2 - 23s + 26 = A(s-2)(s-3) + B(s-1)(s-3) + C(s-1)(s-2)$$

$$5s^2 - 23s + 26 = A(s^2 - 3s - 2s + 6) + B(s^2 - 3s - s + 3) + C(s^2 - 2s - s + 2)$$

$$5s^2 - 23s + 26 = As^2 - 5As + 6A + Bs^2 - 4Bs + 3B + Cs^2 - 3Cs + 2C$$

$$5s^2 = As^2 + Bs^2 + Cs^2 \rightarrow A + B + C = 5 \quad \dots \dots \dots 1$$

$$-23s = -5As - 4Bs - 3Cs$$

$$-23 = -5A - 4B - 3C \quad \dots \dots \dots 2$$

$$26 = 6A + 3B + 2C$$

..... 3

$$(A + B + C = 5) * -2$$

$$6A + 3B + 2C = 26$$

$$-2A - 2B - 2C = -10$$

$$6A + 3B + 2C = 26$$

$$4A + B = 16 \rightarrow 4A = 16 - B \rightarrow A = \frac{16 - B}{4} \dots \dots \dots \quad 1$$

$$A + B + C = 5 \rightarrow \frac{16 - B}{4} + B + C = 5 \rightarrow \frac{16 - B + 4B}{4} + C = 5 \rightarrow \frac{16 + 3B}{4} + C = 5$$

$$4 + \frac{3}{4}B + C = 5 \rightarrow C = 1 - \frac{3}{4}B \dots \dots \quad 2$$

$$-23 = -5A - 4B - 3C \rightarrow -23 = -5\left(\frac{16 - B}{4}\right) - 4B - 3\left(1 - \frac{3}{4}B\right)$$

$$-23 = \frac{-5 \times 16 + 5B}{4} - 4B - 3 + \frac{9}{4}B$$

$$-23 + 3 = -20 + \frac{5}{4}B - 4B + \frac{9}{4}B \rightarrow -20 = -20 + \frac{14}{4}B - 4B \rightarrow 0 = \frac{-2}{4}B \rightarrow$$

$B = 0$ sub in 1&2

$$A=4, \quad B=0, \quad C=1$$

$$x' = \frac{4}{s-1} + 0 + \frac{1}{s-3}$$

$$x = 4e^t + e^{3t}$$