



**AL- MUSTAQBAL UNIVERSITY COLLEGE**  
**DEPARTMENT OF BIOMEDICAL ENGINEERING**

**Digital Signal Processing (DSP)**  
**BME 312**

**Lecture 6**

**- Continuous Time Signal -**

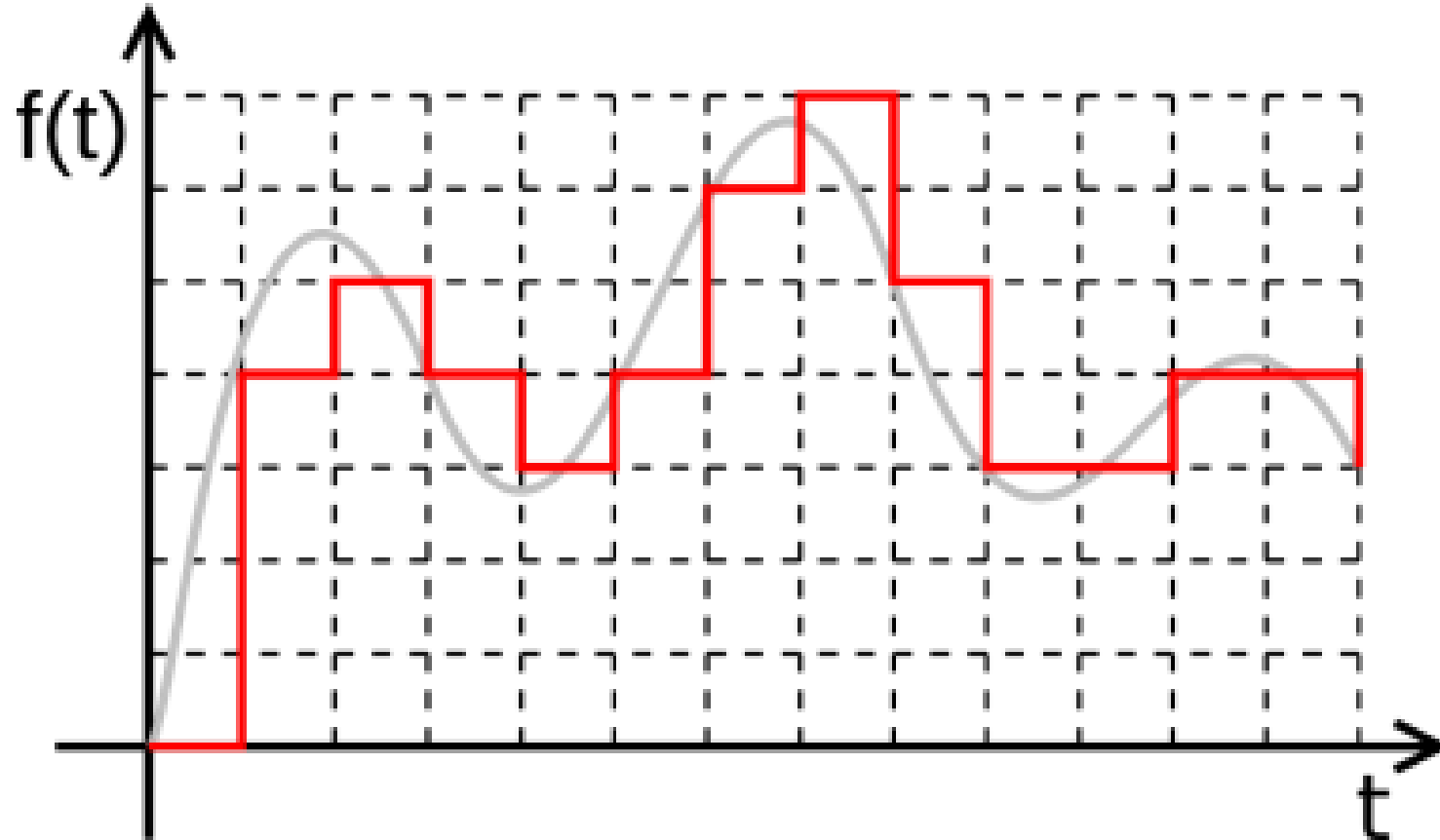
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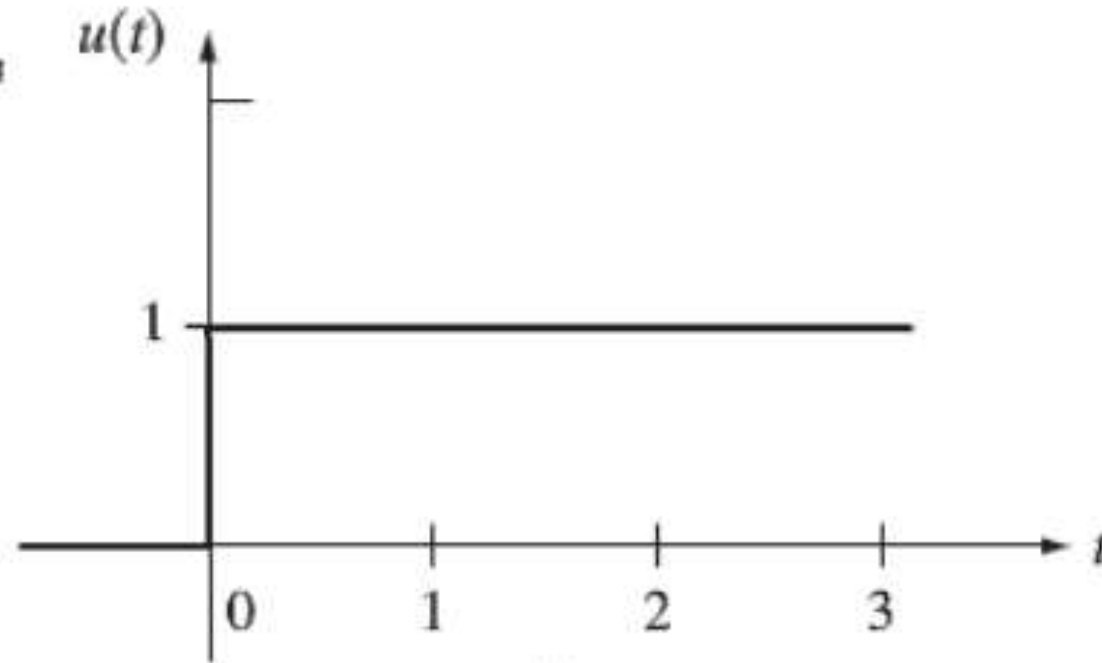
# Continuous Time Signal

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# Unit - Step Function $u(t)$

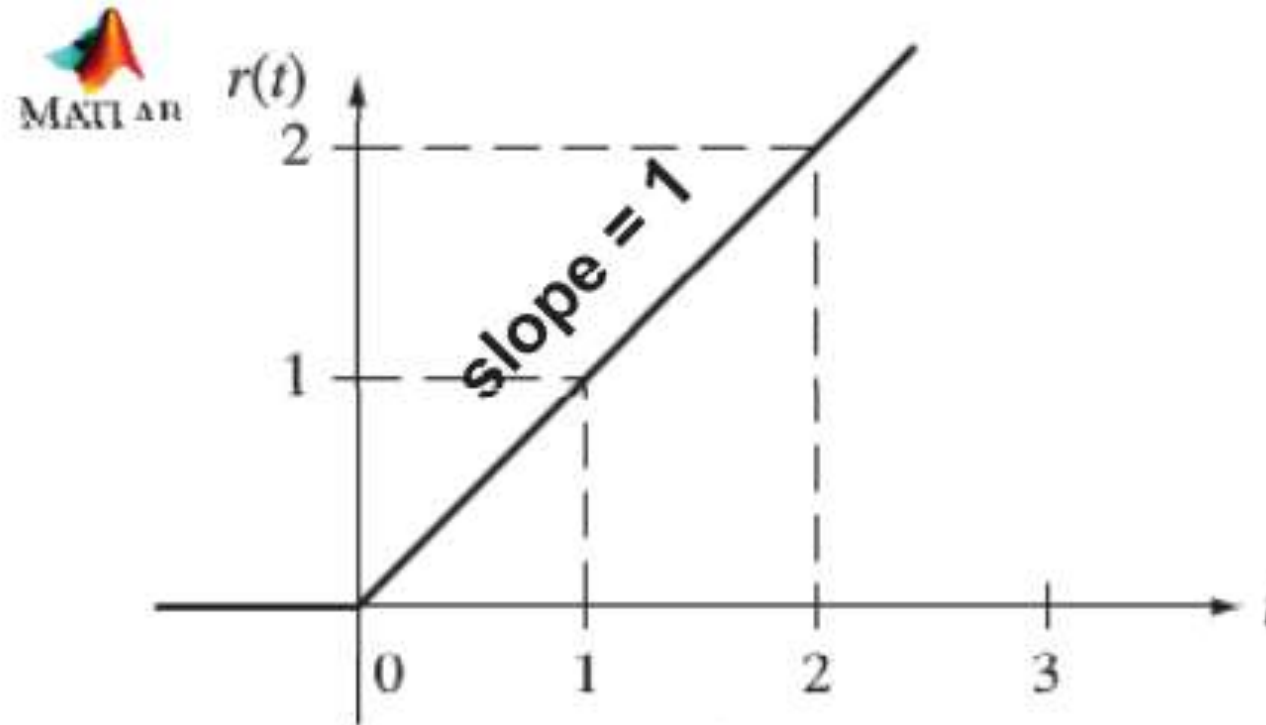
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$$u(t) = \begin{cases} 1, & t \geq 0 \\ 0, & t < 0 \end{cases}$$

# Unit - Ramp Function $r(t)$

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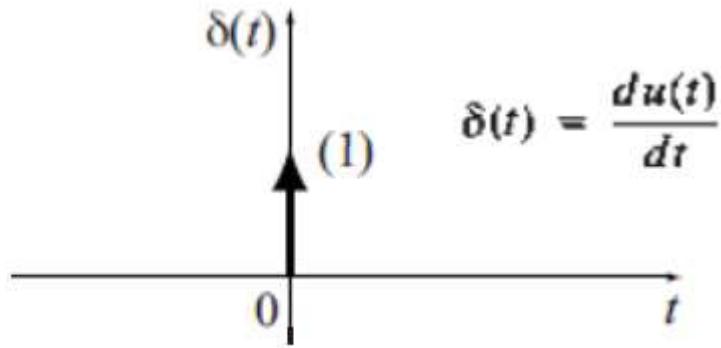
$$r(t) = \begin{cases} t, & t \geq 0 \\ 0, & t < 0 \end{cases}$$

# Unit Impulse

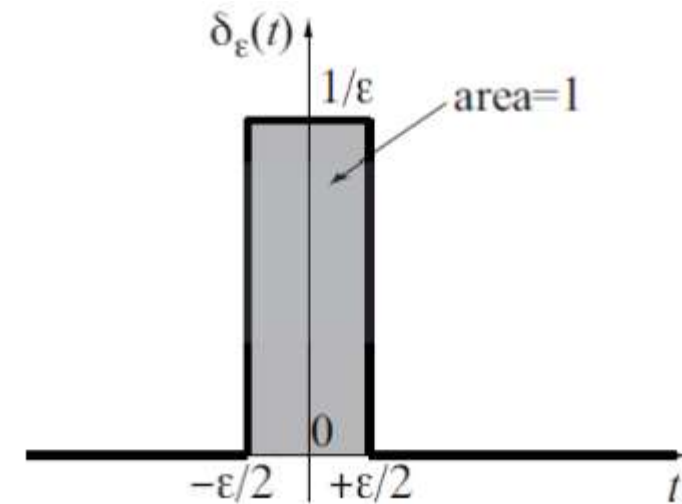


The unit impulse also called the delta function or the Dirac distribution, is defined by

$$\delta(t) = 0 \text{ for } t \neq 0$$



$$\delta[n] = \begin{cases} 1 & n = 0 \\ 0 & n \neq 0 \end{cases}$$



where  $\delta(t) = \lim_{\epsilon \rightarrow 0} \delta_\epsilon(t),$

$$\delta_\epsilon(t) = \begin{cases} 1/\epsilon, & -\epsilon/2 \leq t \leq \epsilon/2 \\ 0, & |t| > \epsilon/2 \end{cases}$$

# Unit Impulse



If  $x(t)$  is a signal that is continuous at  $t = 0$ , then

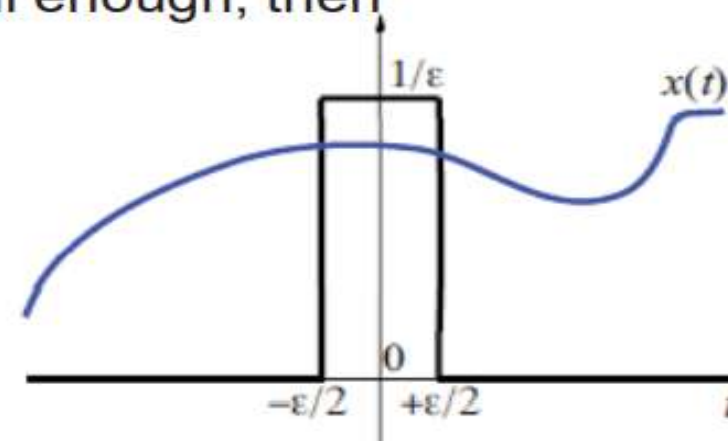
$$x(t)\delta(t) = x(0)\delta(t)$$

In particular,

$$\int_{-a}^a x(t)\delta(t)dt = x(0) \quad \text{for any } 0 < a \leq +\infty.$$

You can convince yourselves of this by approximating  $\delta(t)$  with a pulse, such as  $\delta_s(t)$ , and using the fact that, if  $s$  is small enough, then

$$x(t) \approx x(0) \quad \text{for } -\varepsilon/2 \leq t \leq \varepsilon/2.$$

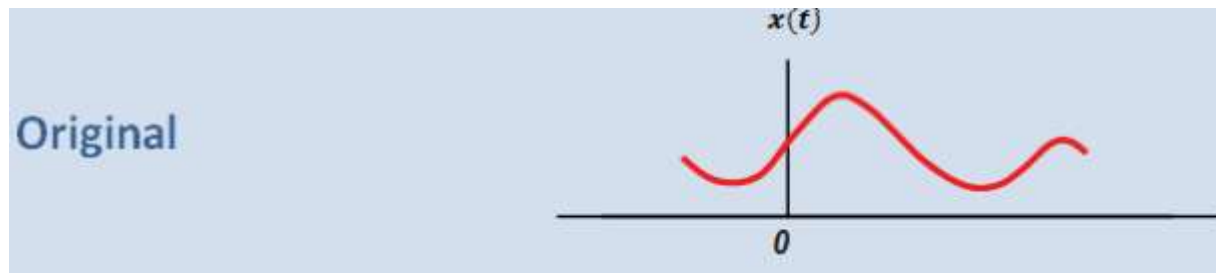


# Transformations of time: Time-Shifted Signals



To consider the time-shifted version of  $x(t)$ , use the following rules:

The signal  $x(t - t_0)$  is  $x(t)$  shifted to the right by  $t_0$  seconds.

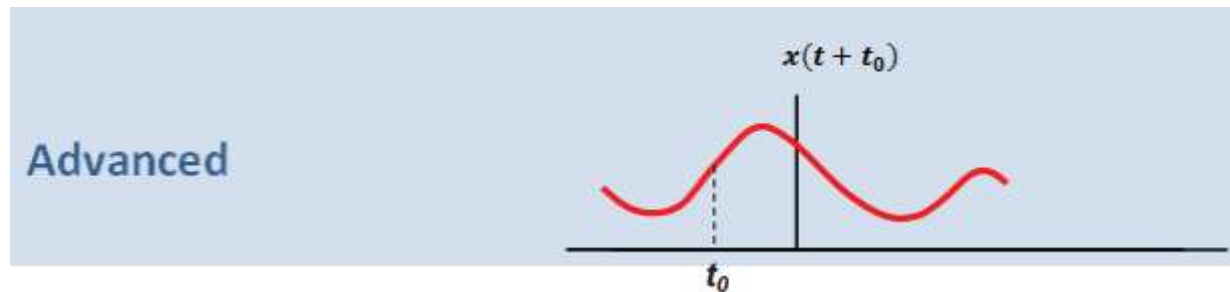
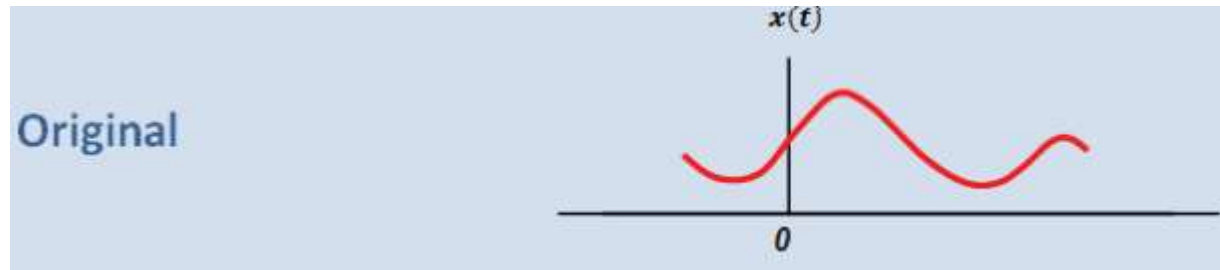


# Transformations of time: Time-Shifted Signals



To consider the time-shifted version of  $x(t)$ , use the following rules:

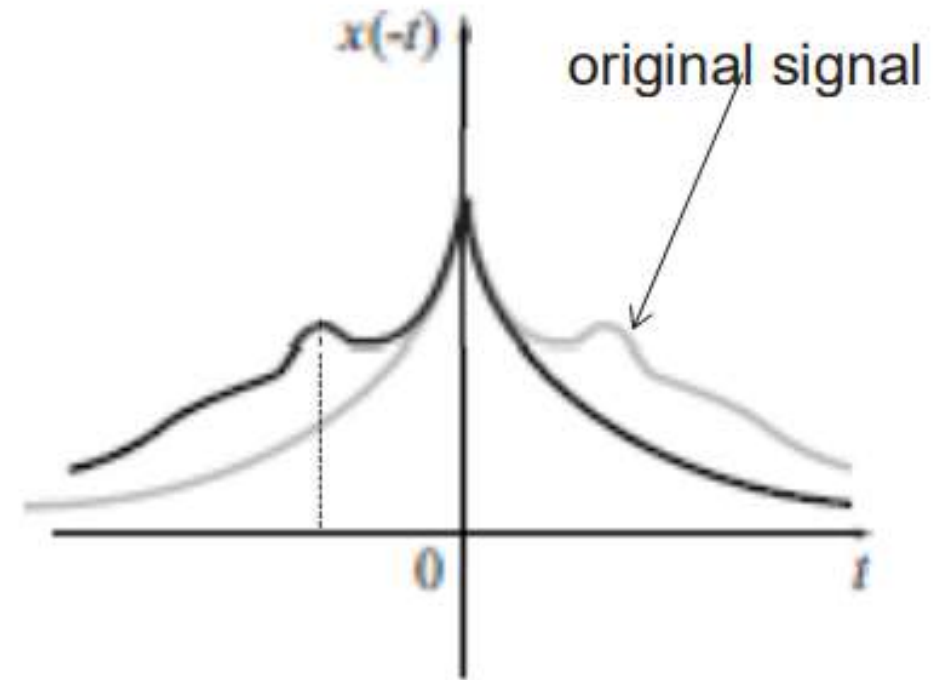
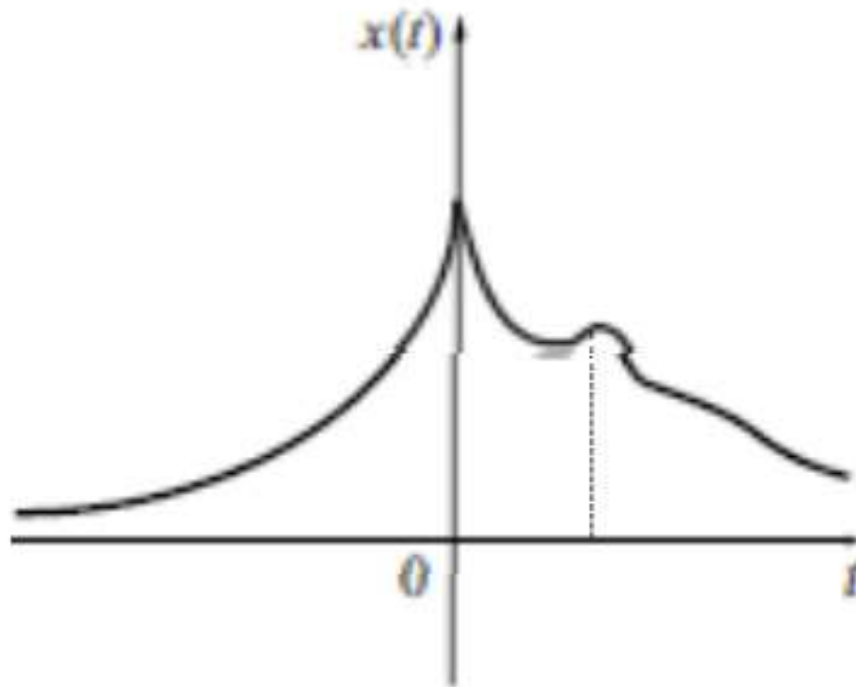
The signal  $x(t + t_0)$  is  $x(t)$  shifted to the left by  $t_0$  seconds.





# Transformations of time: Time reversal (Reflection)

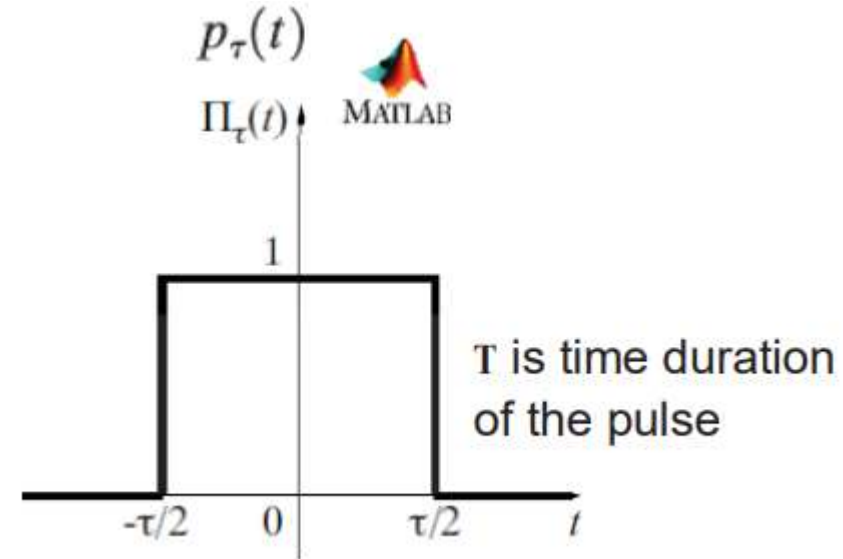
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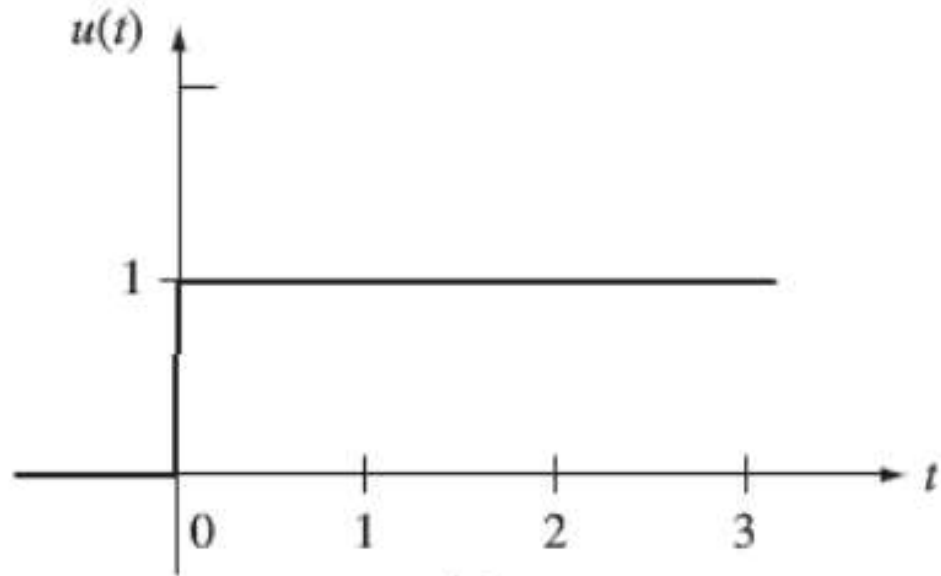
# Rectangular pulse function



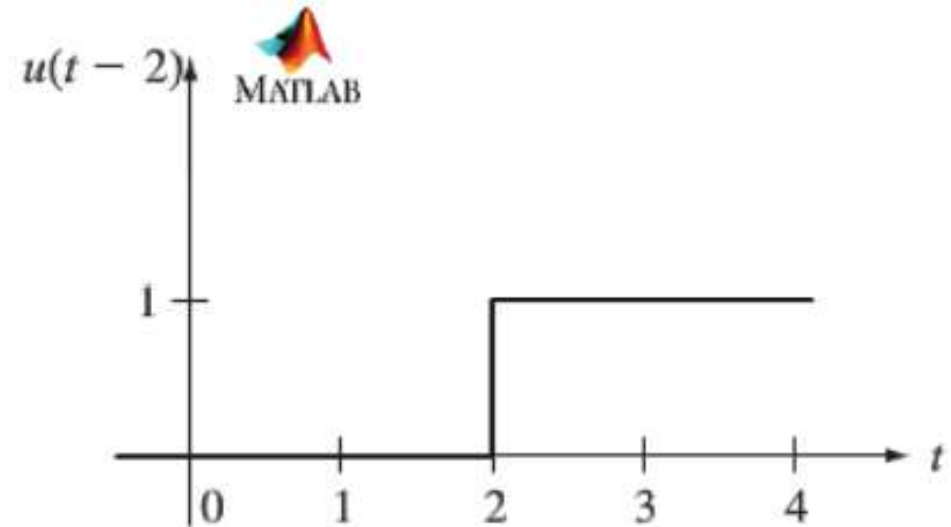
$$p_{\tau}(t) = \begin{cases} 1, & -\frac{\tau}{2} \leq t < \frac{\tau}{2} \\ 0, & t < -\frac{\tau}{2}, t \geq \frac{\tau}{2} \end{cases}$$



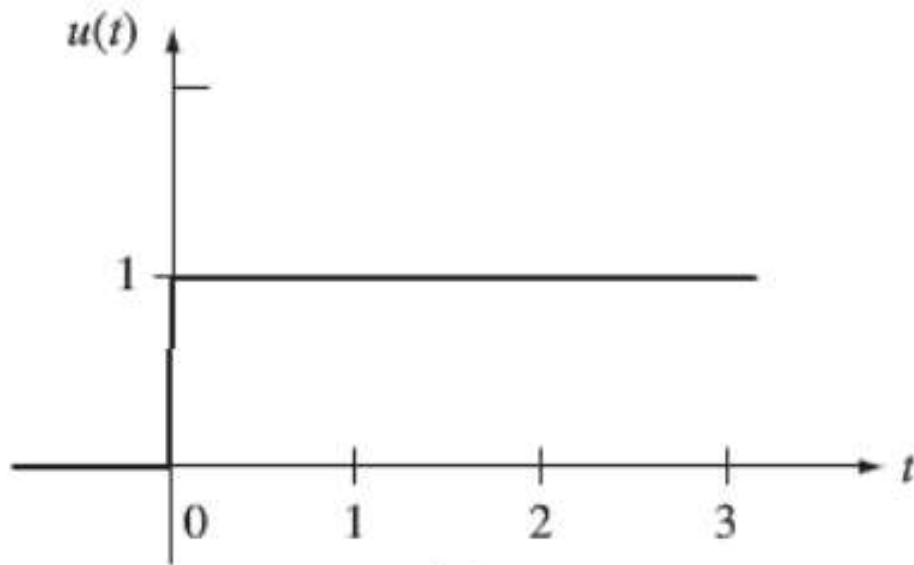
$p_{\tau}(t)$  can be expressed in the form  $\Pi_{\tau}(t) = u\left(t + \frac{\tau}{2}\right) - u\left(t - \frac{\tau}{2}\right)$



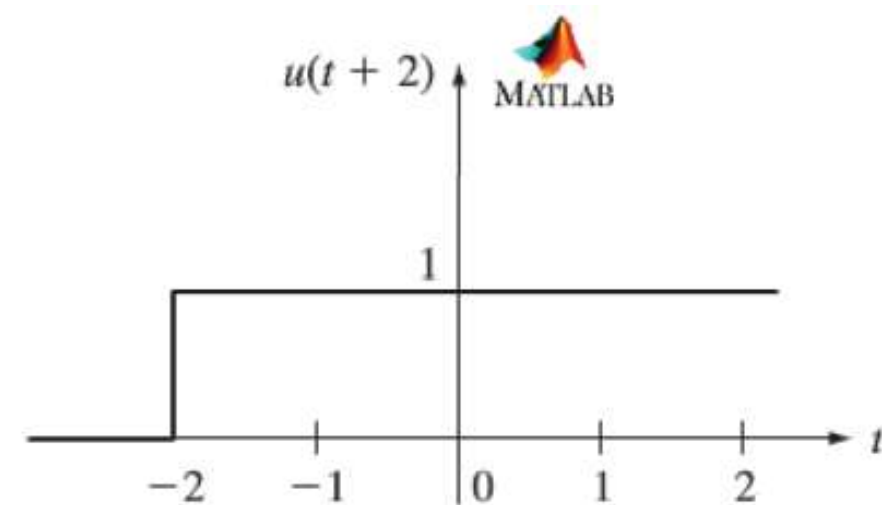
$$u(t) = \begin{cases} 1, & t \geq 0 \\ 0, & t < 0 \end{cases}$$



**2 second right shift of u(t)**



$$u(t) = \begin{cases} 1, & t \geq 0 \\ 0, & t < 0 \end{cases}$$

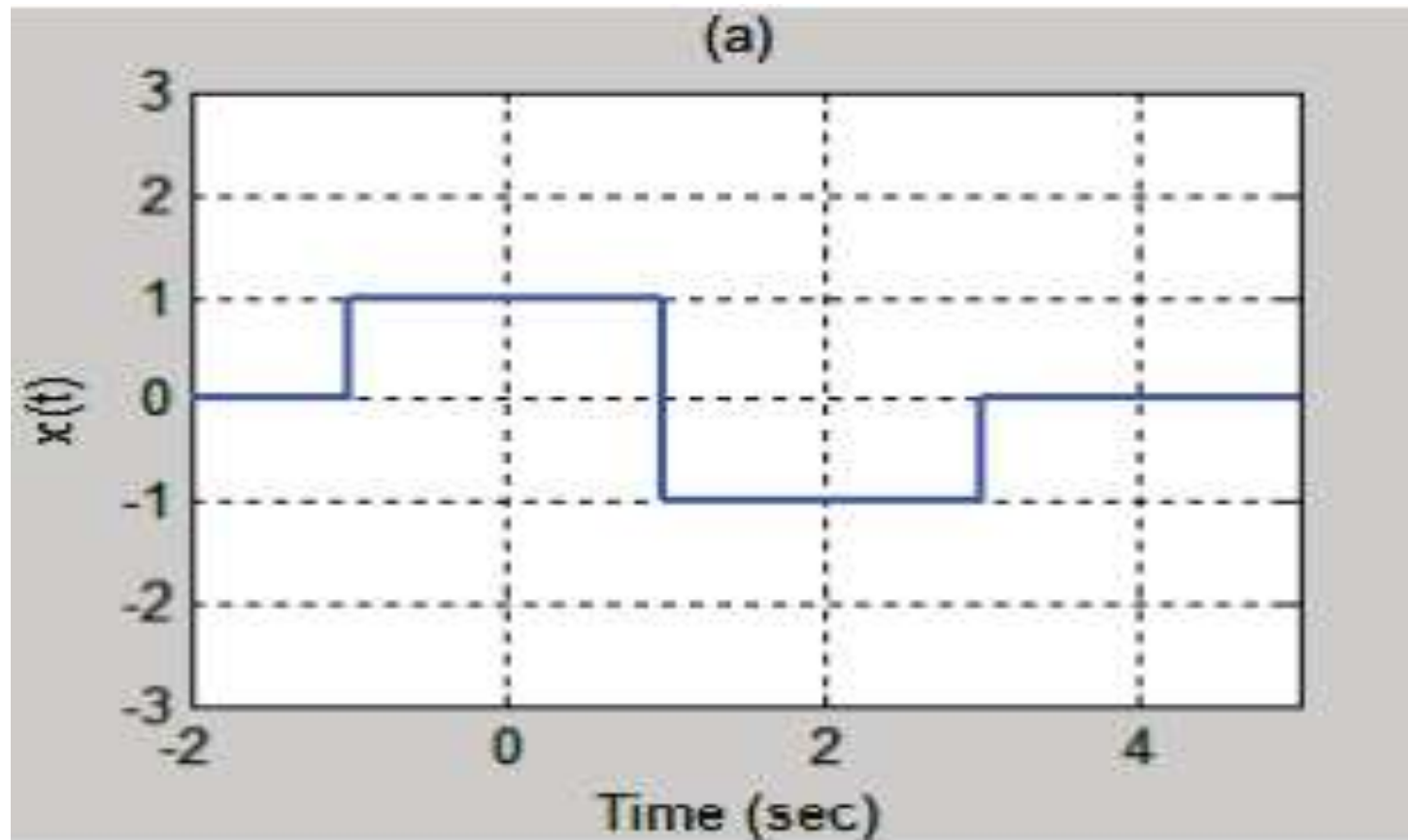


**2 second left shift of  $u(t)$**

# Example 1



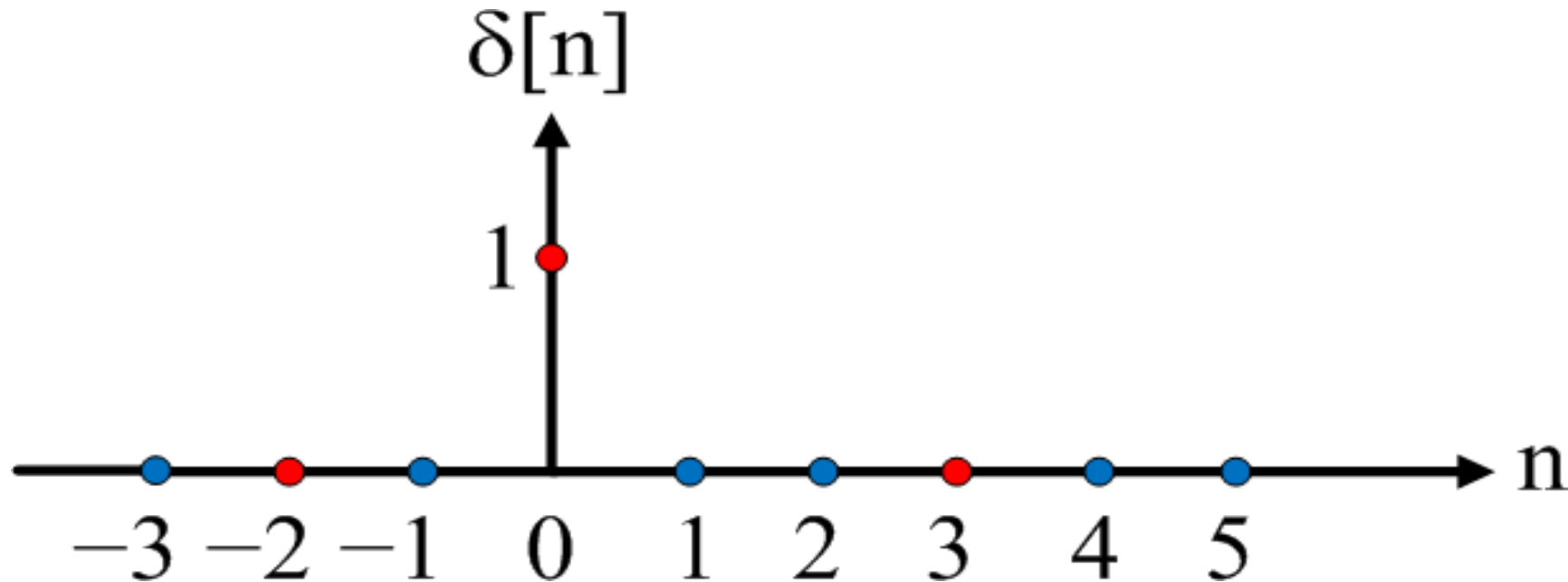
$$x(t) = u(t + 1) - 2u(t - 1) + u(t - 3)$$



## Example 2



Determine the values  $\delta[0]$ ,  $\delta[3]$  and  $\delta[-2]$ .

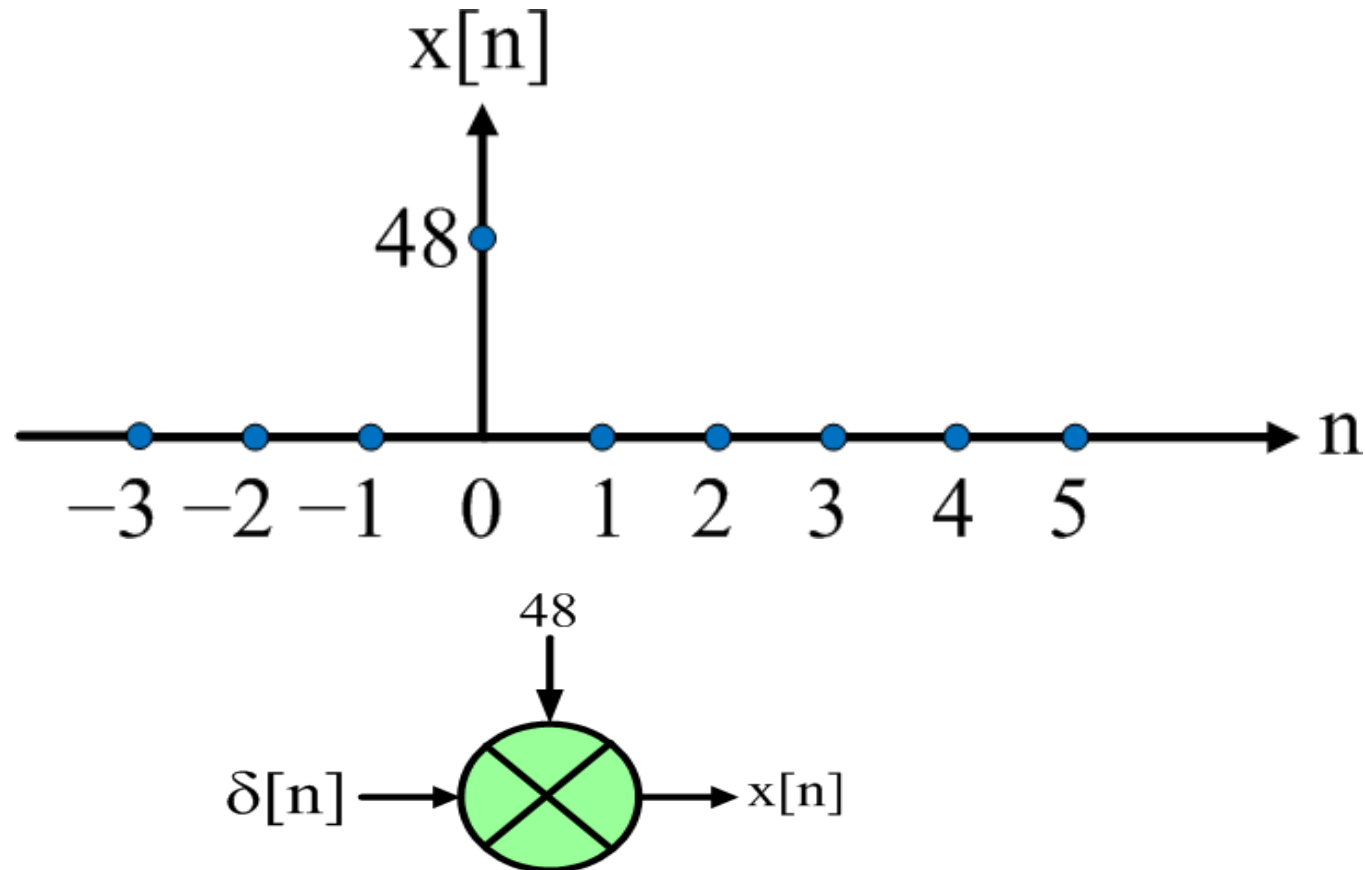


$$\delta[0] = 1, \delta[3] = 0 \text{ and } \delta[-2] = 0$$

## Example 3



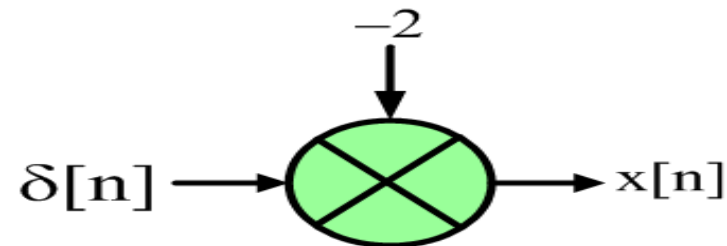
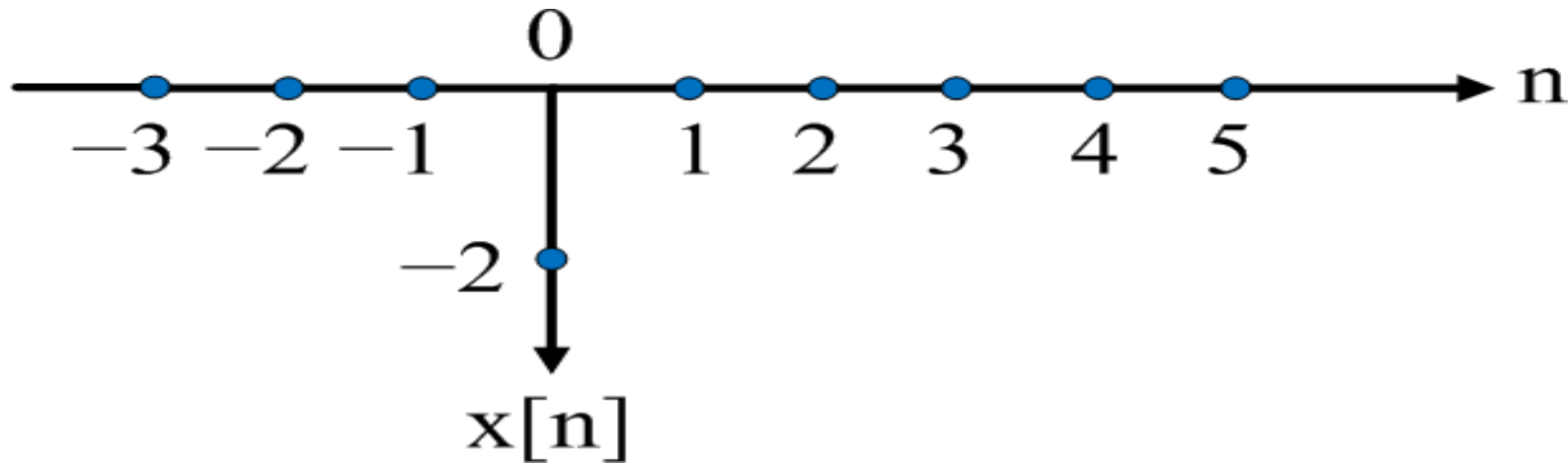
$$x[n] = 48\delta[n]$$



## Example 4



$$x[n] = -2\delta[n]$$

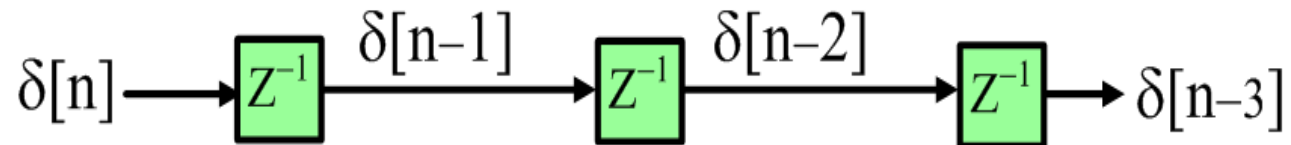
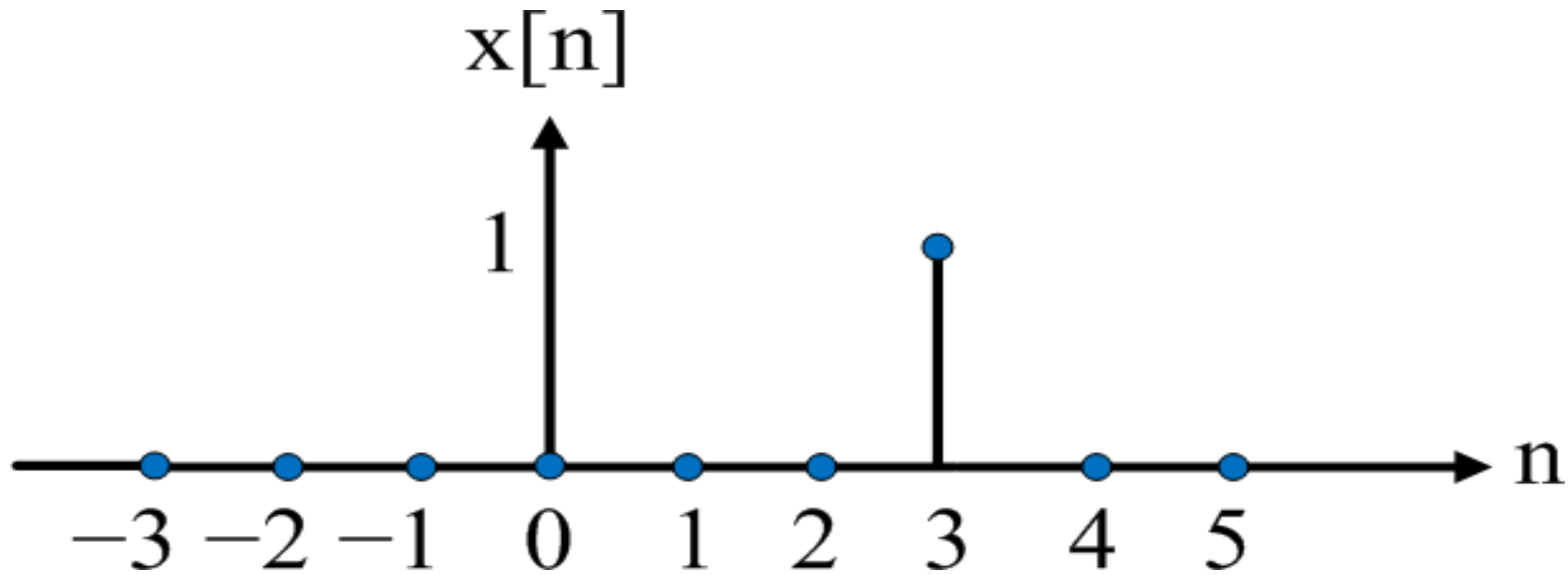




## Example 5



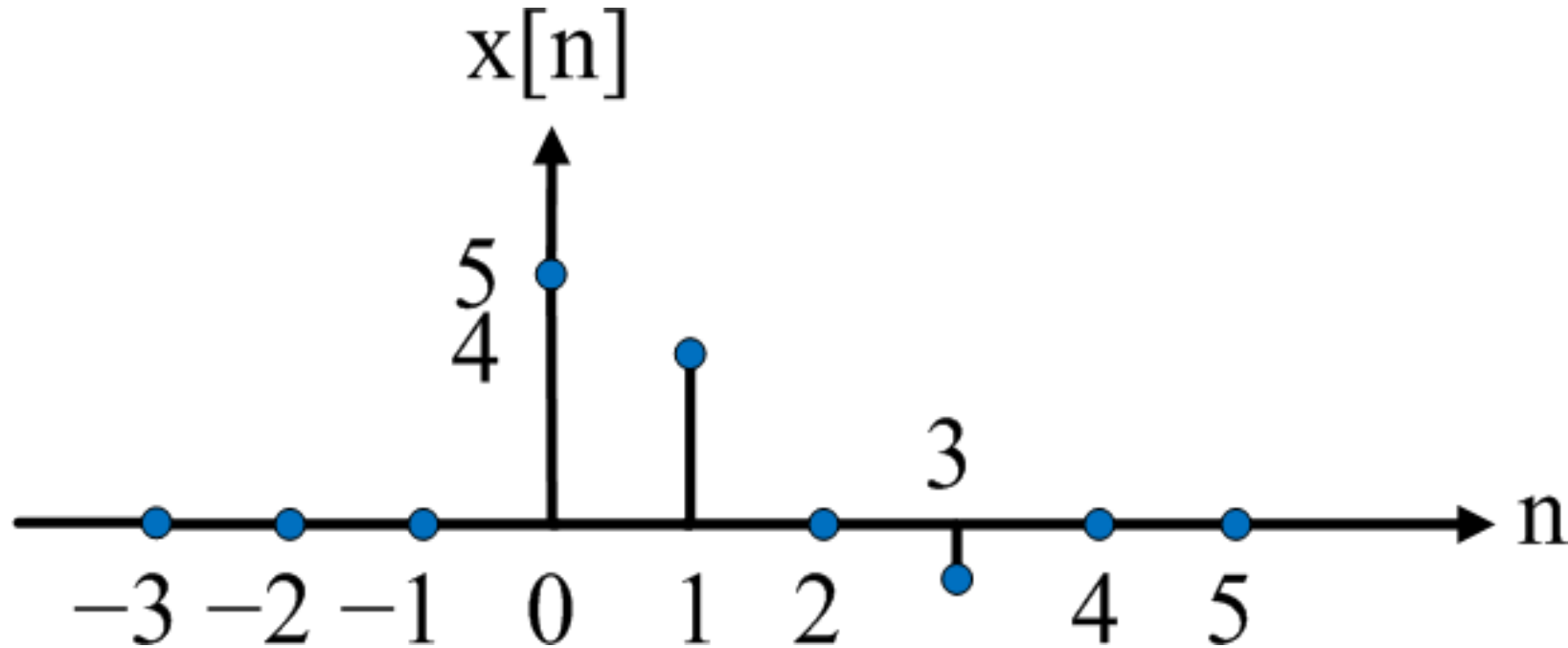
$$x[n] = \delta[n - 3]$$



## Example 6



$$x[n] = 5\delta[n] + 4\delta[n - 1] - \delta[n - 3]$$



## Example 6



$$x[n] = 5\delta[n] + 4\delta[n - 1] - \delta[n - 3]$$

