

#### AL- MUSTAQBAL UNIVERSITY COLLEGE DEPARTMENT OF BIOMEDICAL ENGINEERING

# **Digital Signal Processing (DSP)** BME 312

#### Lecture 5

### - Convolution I -

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Convolution is a mathematical operation on two functions producing a third function that is affected at any time by all previous input values.

Convolution is the most **important** and fundamental concept in signal processing and analysis. By using convolution, we can **construct the output of any LTI system for any** arbitrary **input** signal, if we know the **impulse response** of that system.

The **impulse response** goes by a different name in some applications. If the **system** being considered **is a** *filter*, the impulse response is called the **filter kernel**, the **convolution kernel**, **or** simply, the **kernel**. In image processing, the impulse response is called the **point spread function**.

#### The convolution is performed by sliding the kernel along the input signal

# Convolution of discrete-time signals

 The convolution of two discrete-time signals x[n] and h[n] to produce a new signal y[n] is denoted by:

$$y[n] = x[n] * h[n]$$

and defined by

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k]$$

This equation referred to as the convolution sum





i. Commutative property:

$$y[n] = h[n] * x[n] = x[n] * h[n]$$

- ii. Associative property  $(x[n]*h_1[n])*h_2[n] = x[n]*(h_1[n]*h_2[n])$
- iii. Distributive property

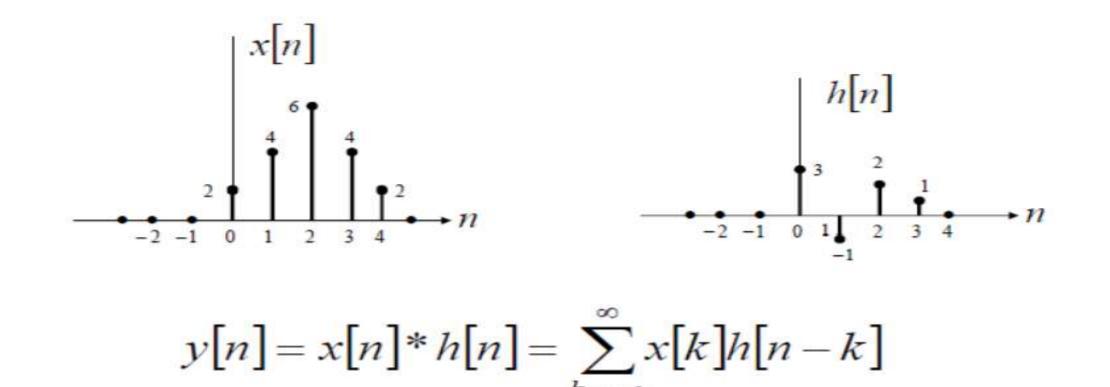
$$x[n]*(h_1[n]+h_2[n]) = x[n]*h_1[n]+x[n]*h_2[n]$$

Example



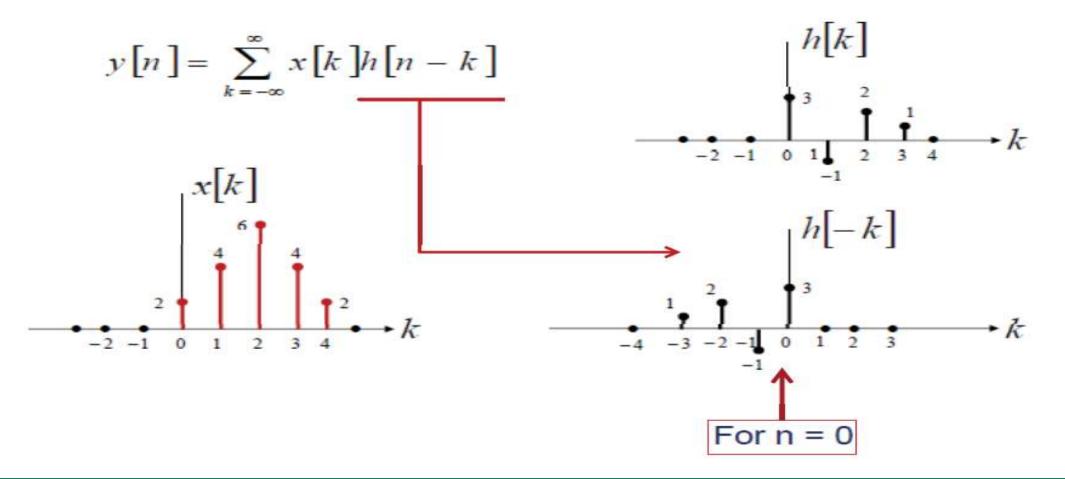


# **Ex.1** Find y[n]=x[n]\*h[n]



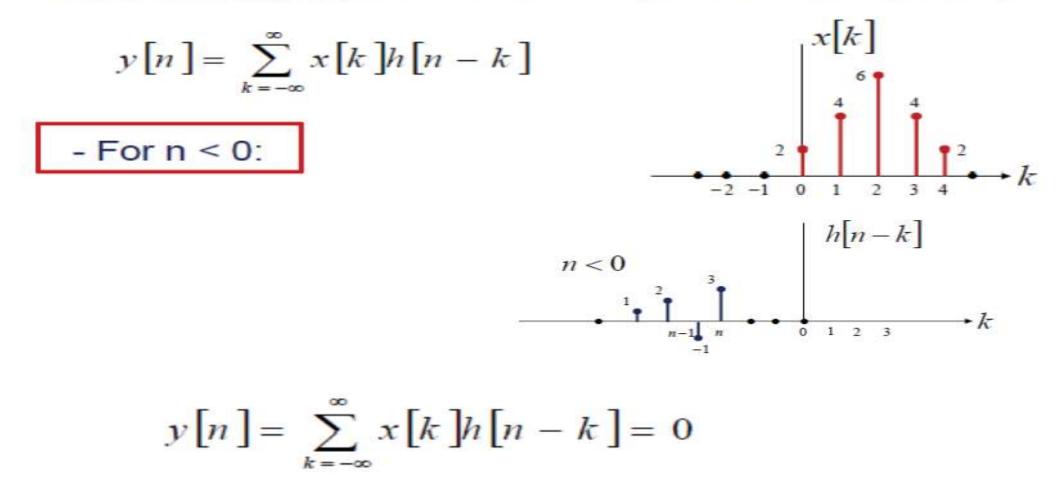
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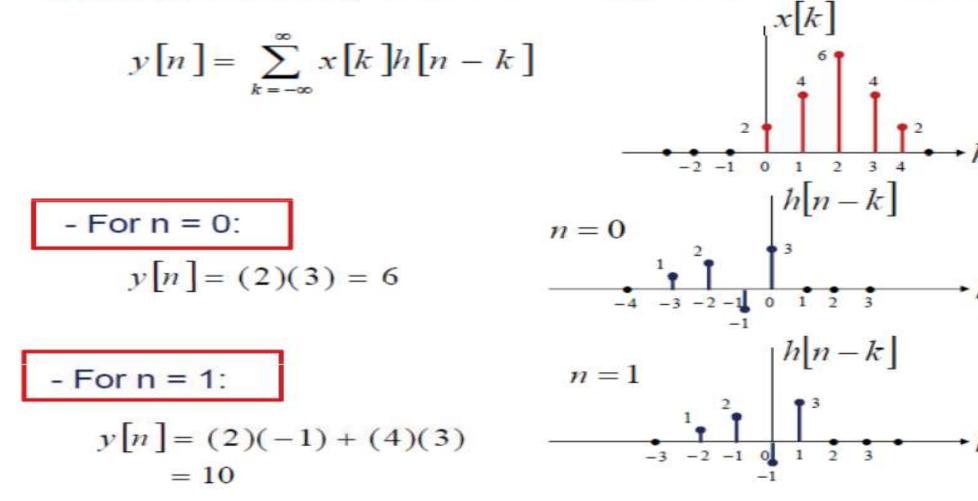
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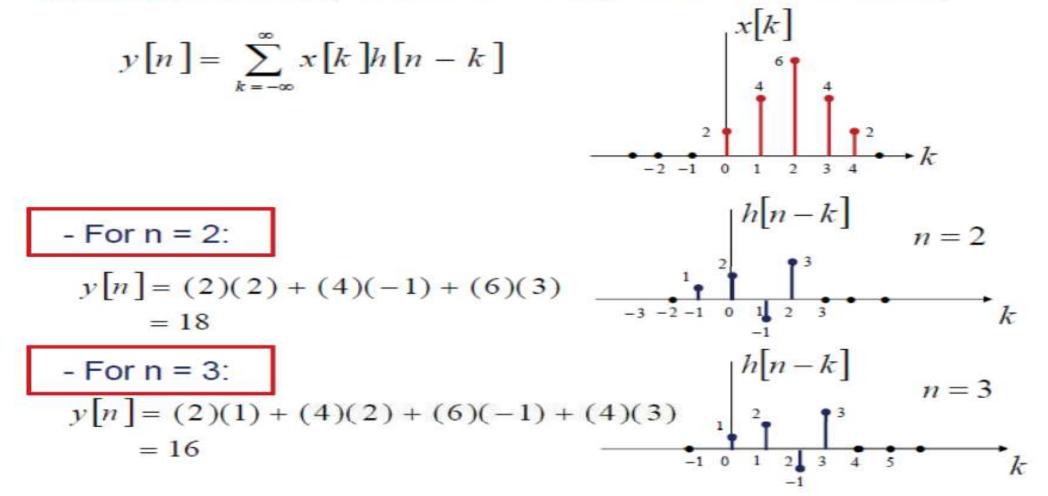








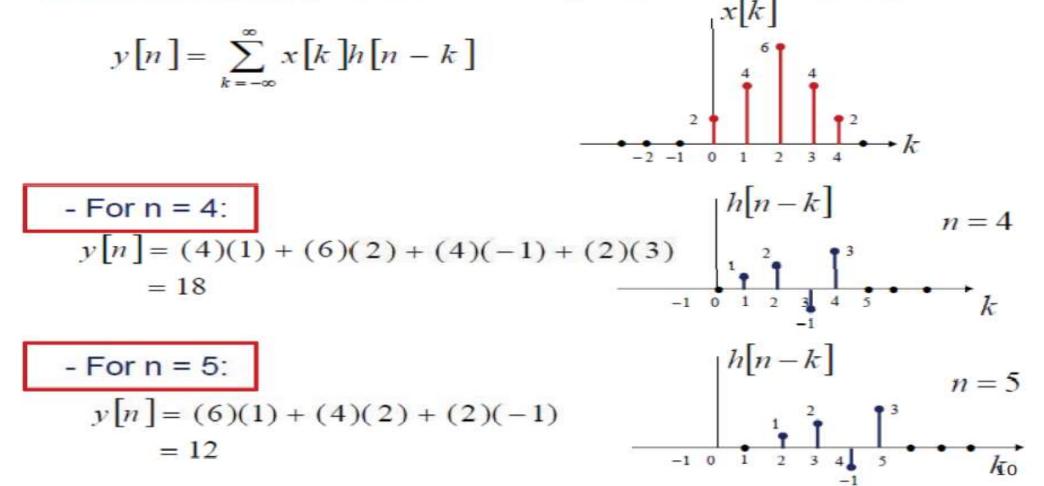






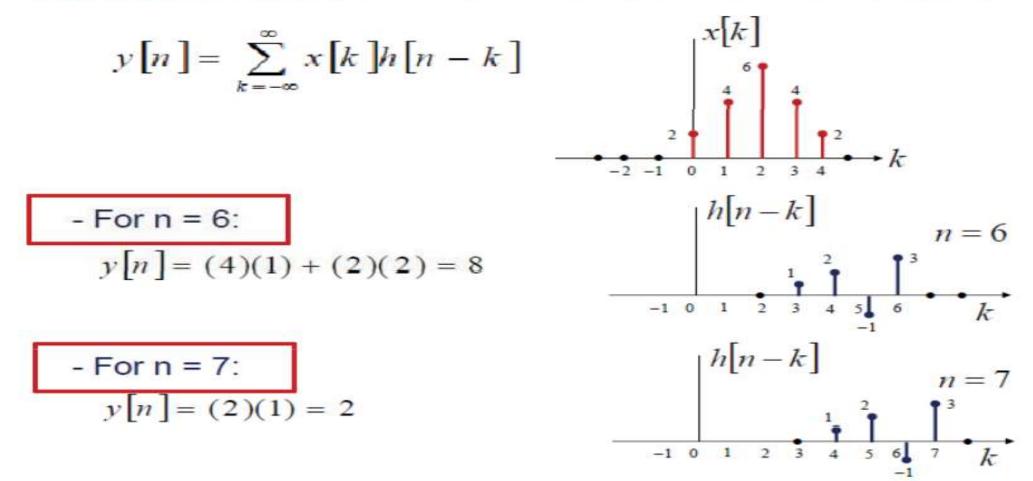








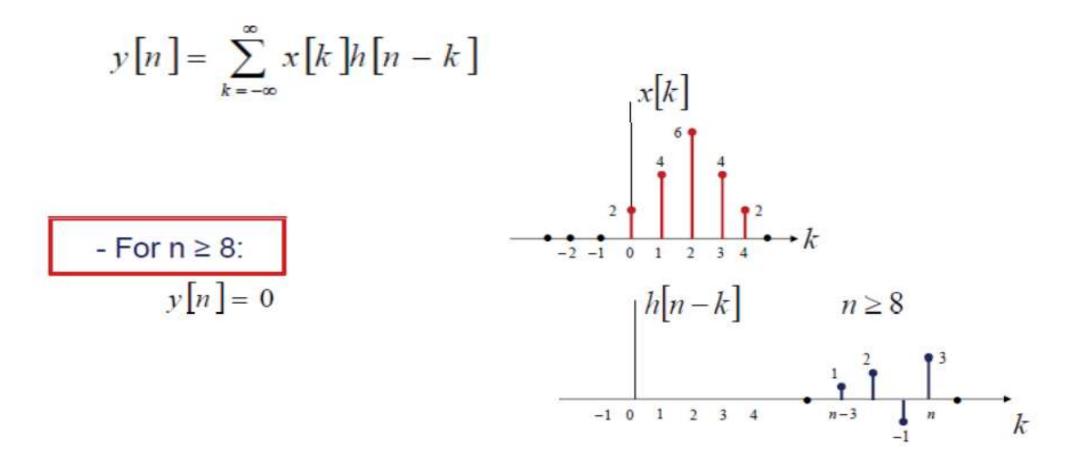




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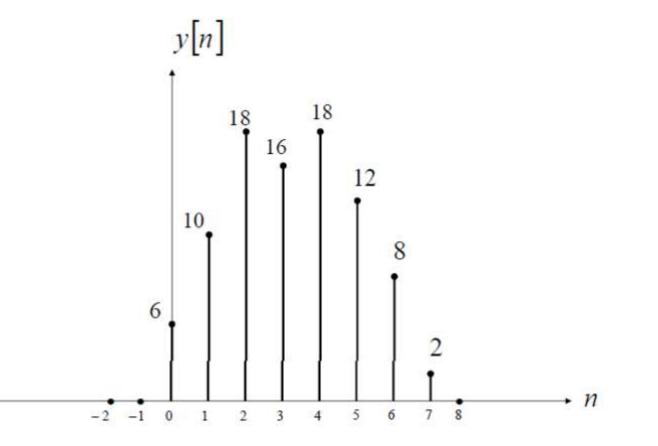
## Solution : Ex.1 (Method 1 - Graphical convolution)



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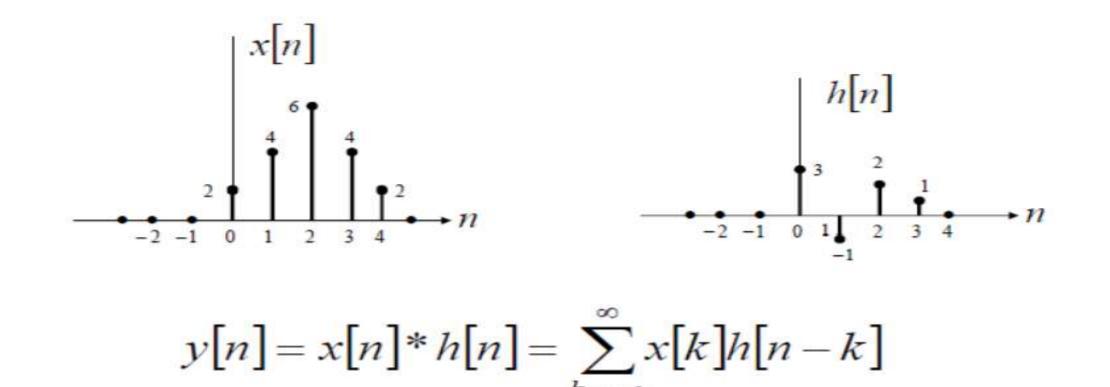


Example





# **Ex.1** Find y[n]=x[n]\*h[n]



# Tabular Method



### Solution : Ex.1 (Method 2 - Tabular method)

First: we denote the nonzero terms of the impulse response h[n] as the

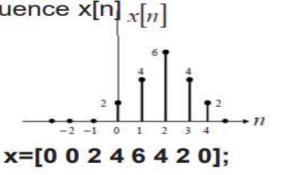
convolution mask

 $h[k] = \{3, -1, 2, 1\}$  $h[k] = \{3, -1, 2, 1\}$ Second: we reverse the order of this convolution mask  $3^{2}$   $-2^{-1} = 0^{-1}$ 

$$h[-k] = \{1, 2, -1, 3\}$$

Third: we slide the reversed convolution mask along the sequence  $x[n]_{x[n]}$ and take the dot product between them for all n. This process is illustrated in the following table for

$$n\chi\{0,1,...,8\}$$

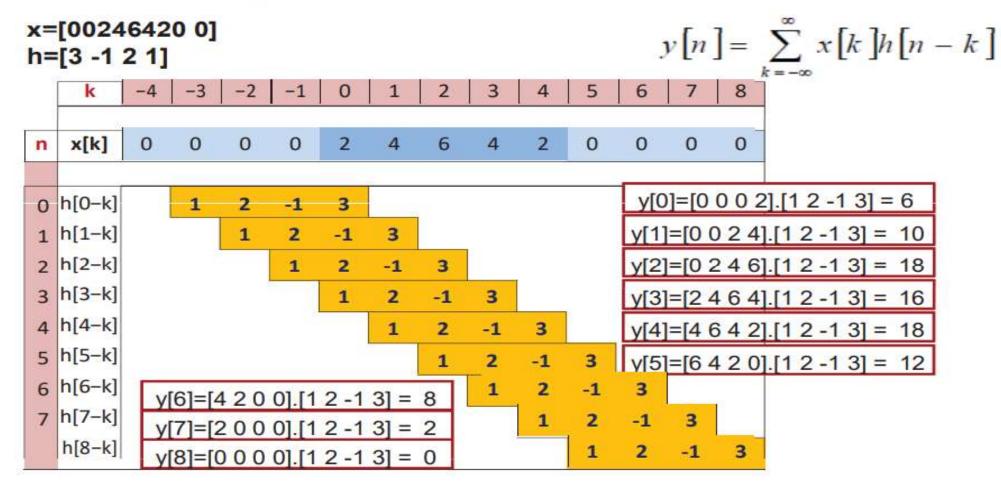


# Tabular Method

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#### Solution : Ex.1 (Method 2 - Tabular method)

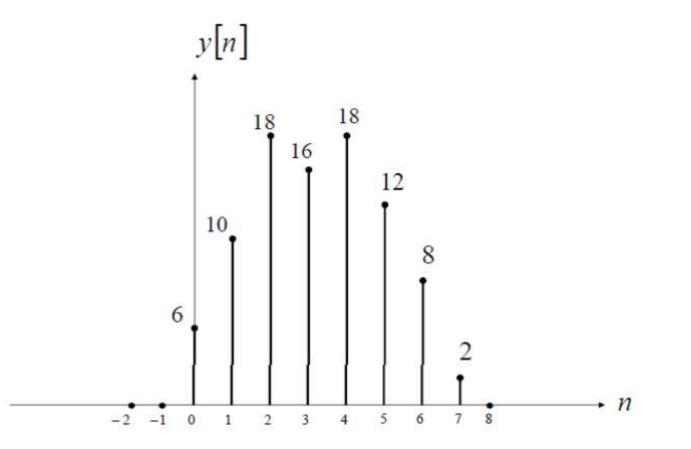


# Tabular Method





#### Solution : Ex.1 (Method 2 - Tabular method)

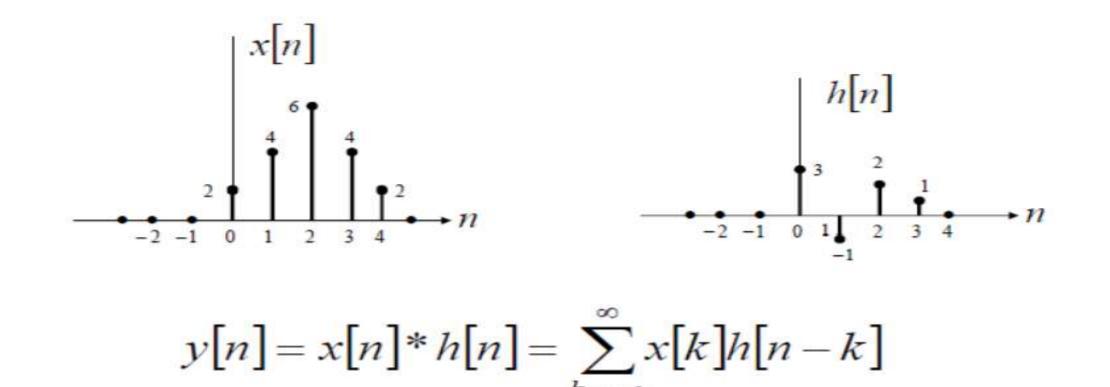


Example





# **Ex.1** Find y[n]=x[n]\*h[n]

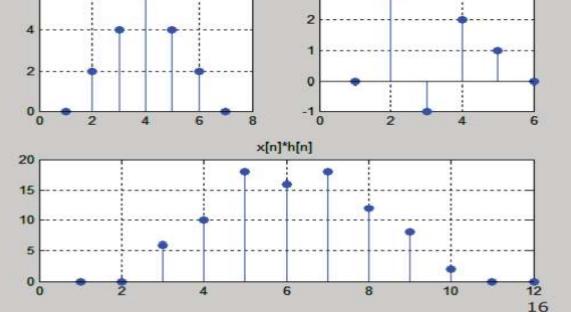


y = conv(x,h);



# Solution : Ex.1 (Method 3 – using MATLAB)

The convolution of two discrete-time signals can be carried out with the MATLAB M-file conv.  $\mathbf{x} = \begin{bmatrix} 0 & 2 & 4 & 6 & 4 & 2 & 0 \end{bmatrix};$  $\mathbf{h} = \begin{bmatrix} 0 & 3 & -1 & 2 & 1 & 0 \end{bmatrix};$ 



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