



AL- MUSTAQBAL UNIVERSITY COLLEGE
DEPARTMENT OF BIOMEDICAL ENGINEERING

Digital Signal Processing (DSP)

BME 312

Lecture 2

- Introduction to DSP -

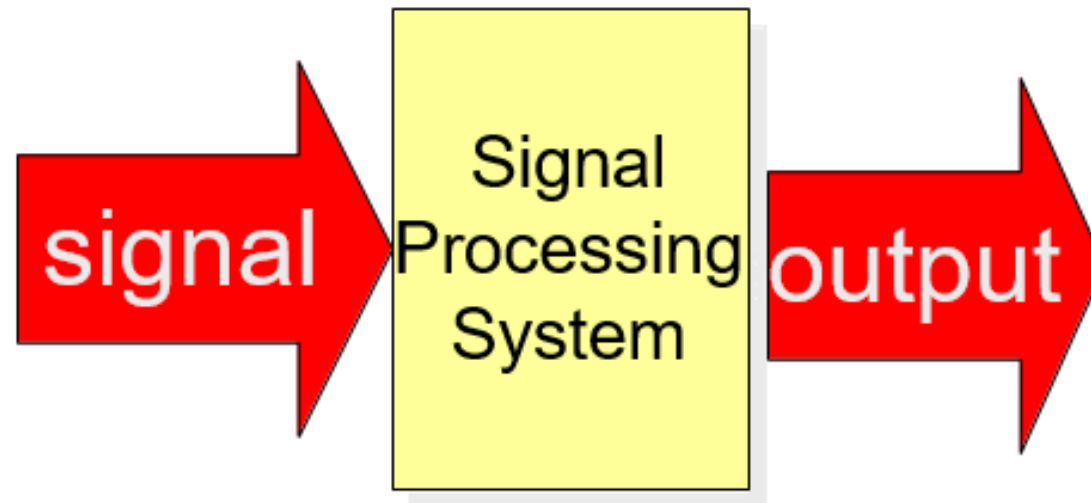
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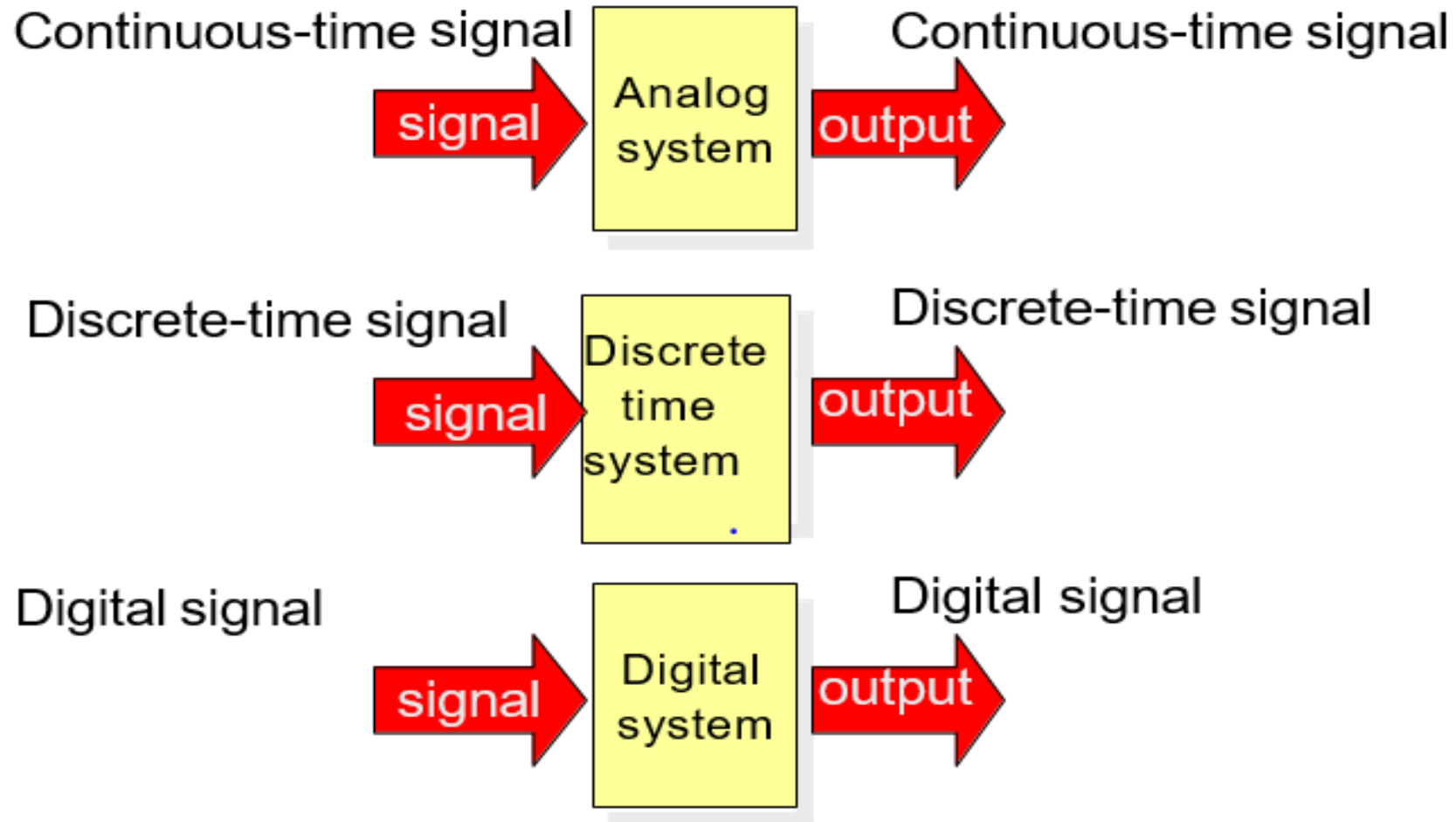
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- A signal is a function of time representing a physical variable, eg: voltage, current etc.
- A signal is defined as a function of one or more independent variables.
 - For example, the function $x(t) = 5t$
 - That signal is represented as a function of an independent variable t (time).
- Signals are functions of independent variables that carry information.



- Facilitate the extraction of desired information.



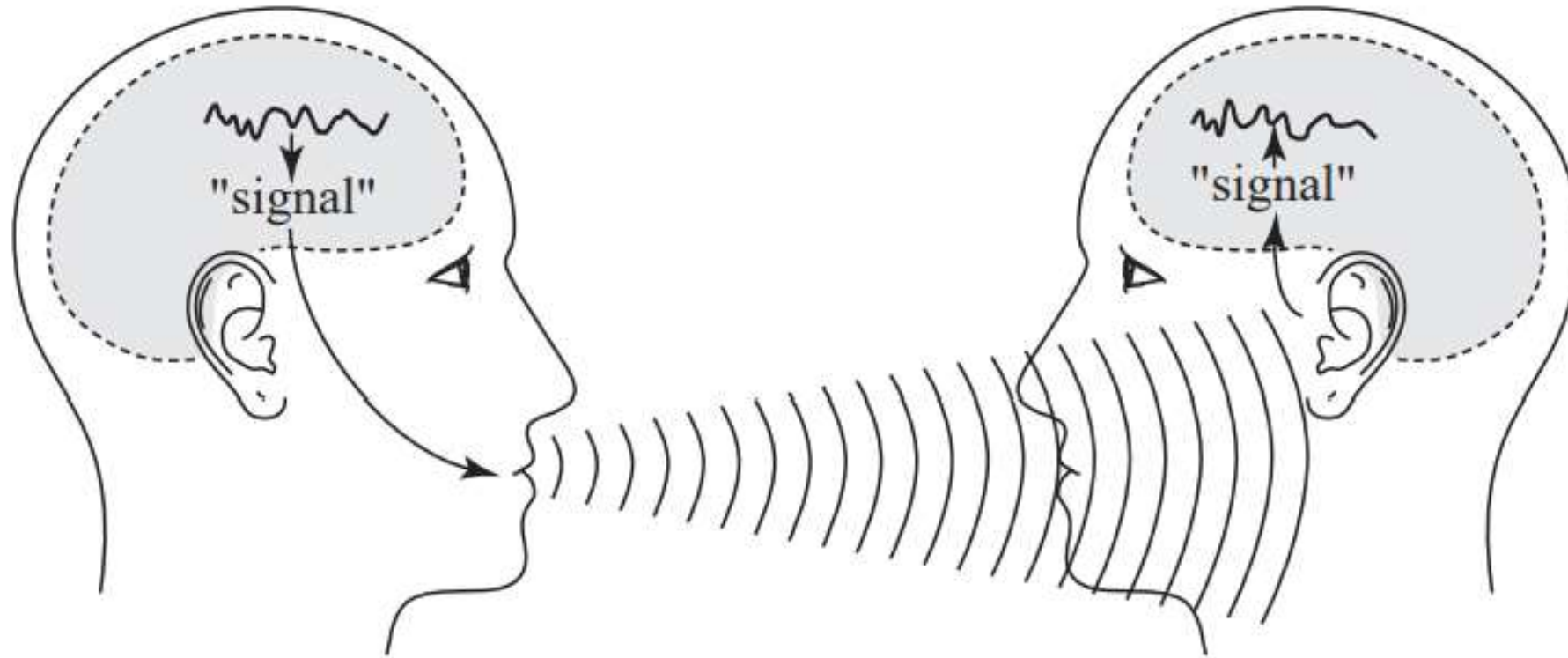


Fig:

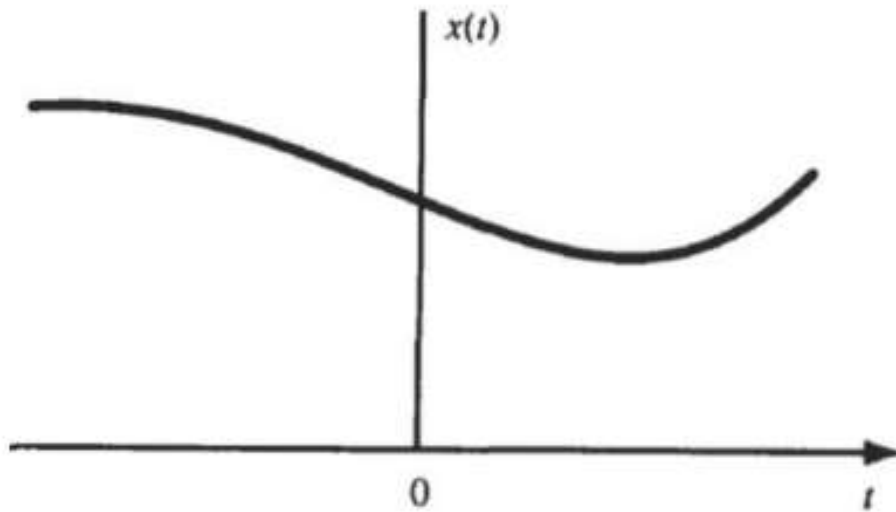
Communication between two people involving signals and signal processing by systems



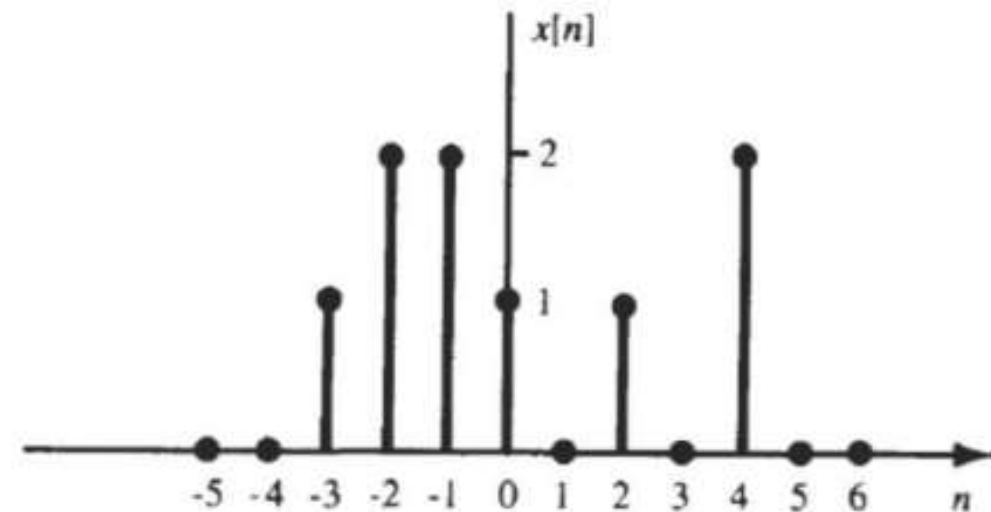
Based on different features for signals, we may identify five methods of classifying signals:

- Continuous-Time and Discrete-Time Signals.
- Analog and Digital Signals.
- Periodic and Non periodic Signals.
- Deterministic and Random Signals.
- Even and Odd Signals.

Continuous-Time and Discrete-Time Signals



(a)



(b)

Fig: Graphical representation of :
(a) Continuous-time and **(b)** Discrete-time signals

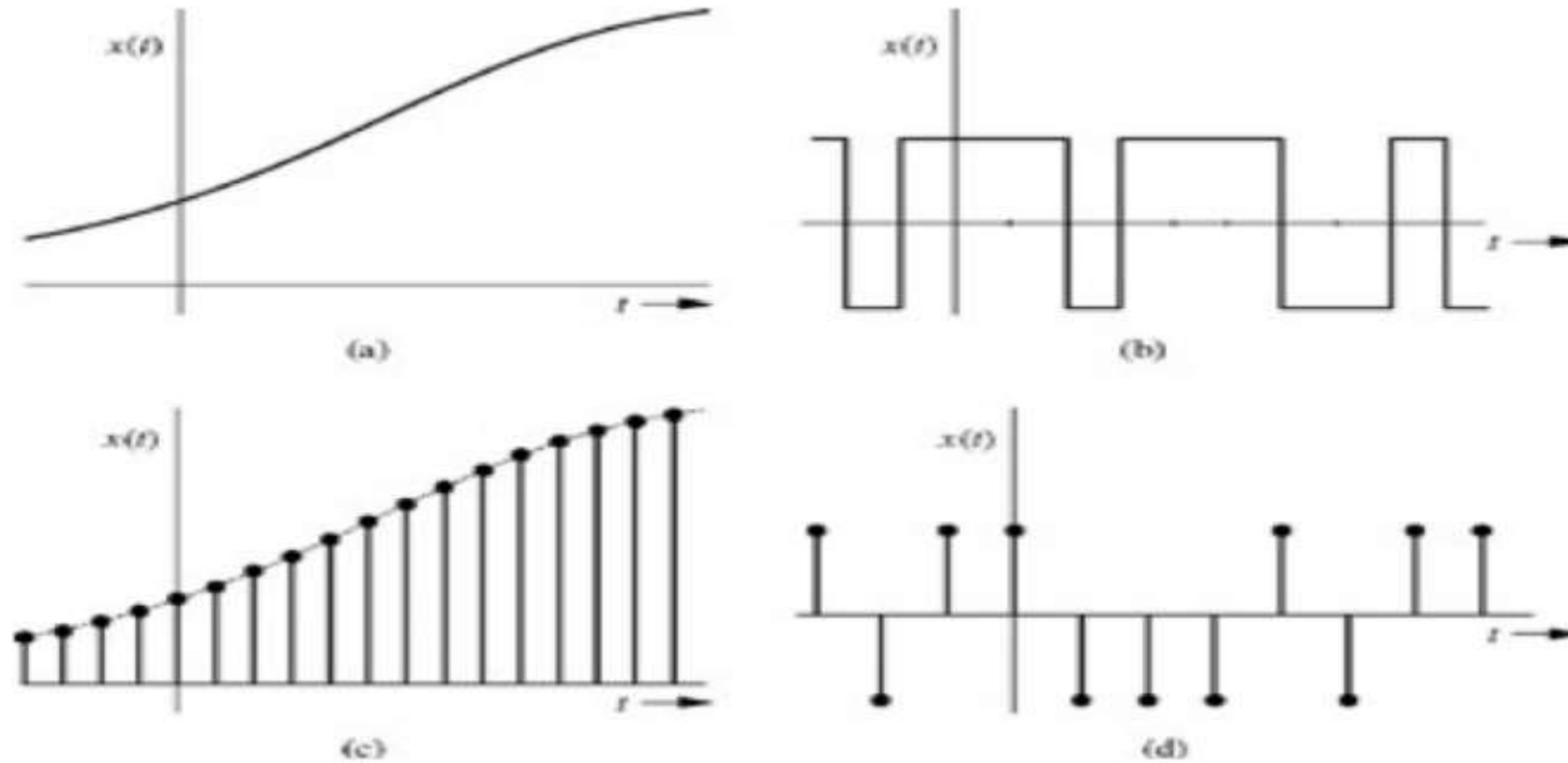
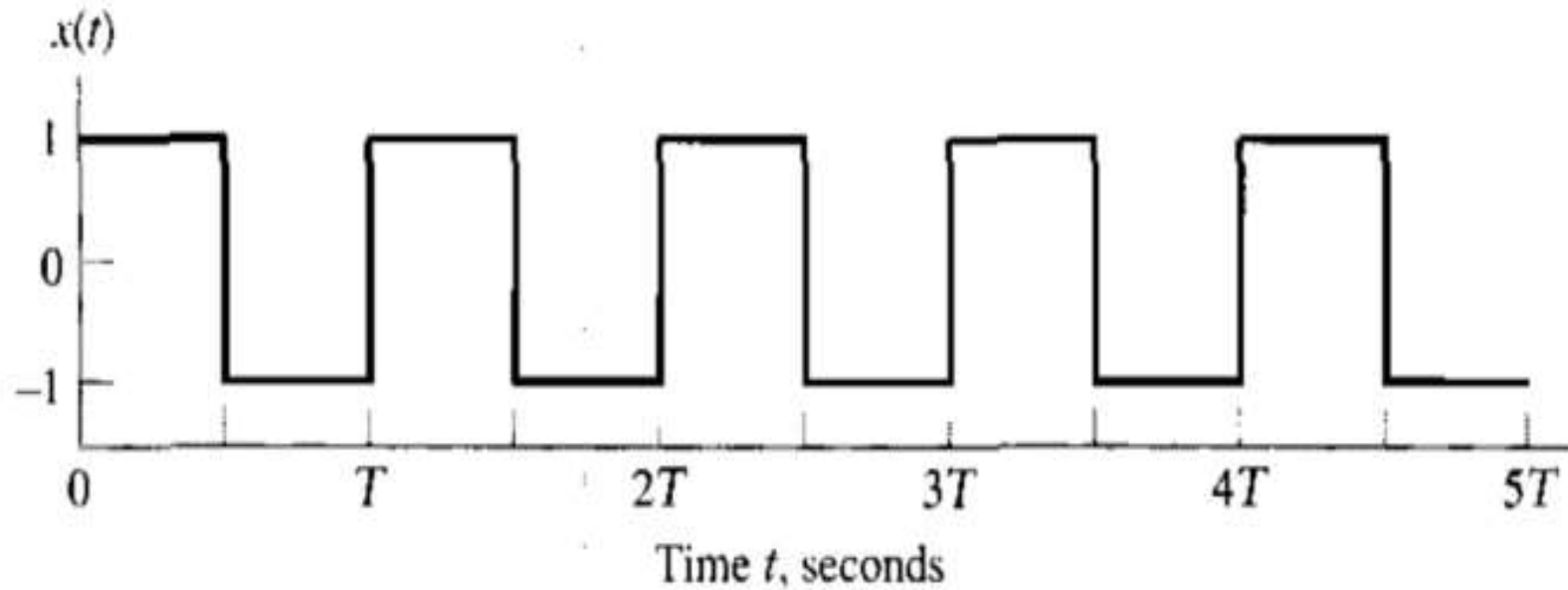
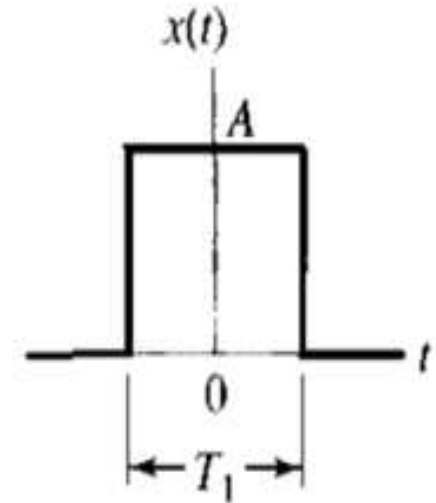


Fig: Graphical representation of:
(a) Analog, continuous time, (b) Digital, continuous time,
(c) Analog, discrete time, and (d) Digital, discrete time

Periodic and Non periodic Signals

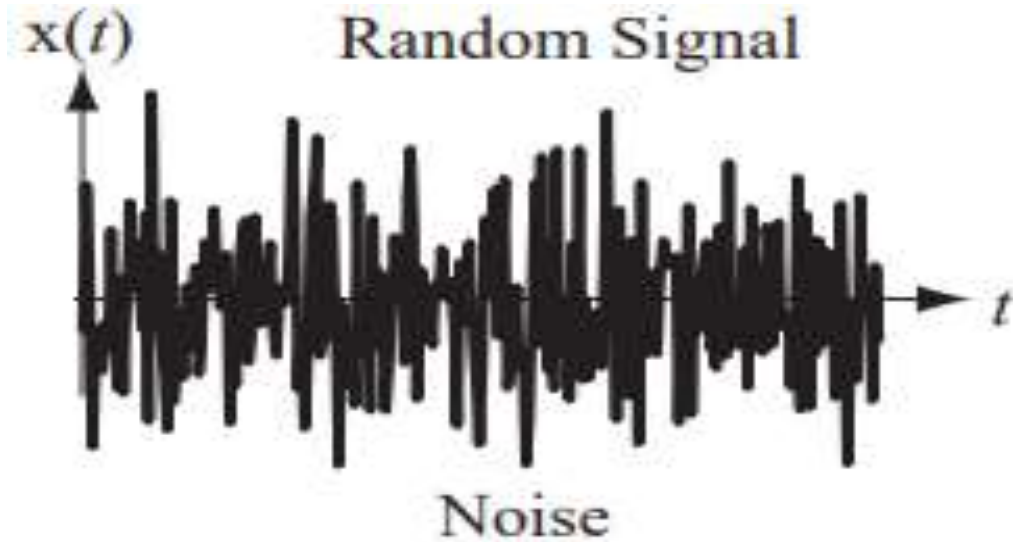


(a)

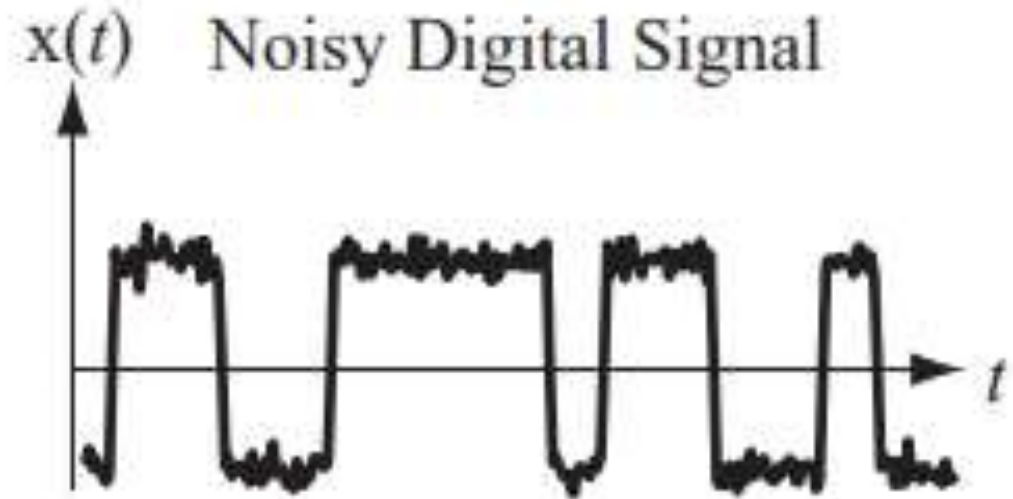


(b)

Fig: Graphical representation of:
(a) Periodic signal, square wave, **(b)** Non periodic, signal rectangular pulse



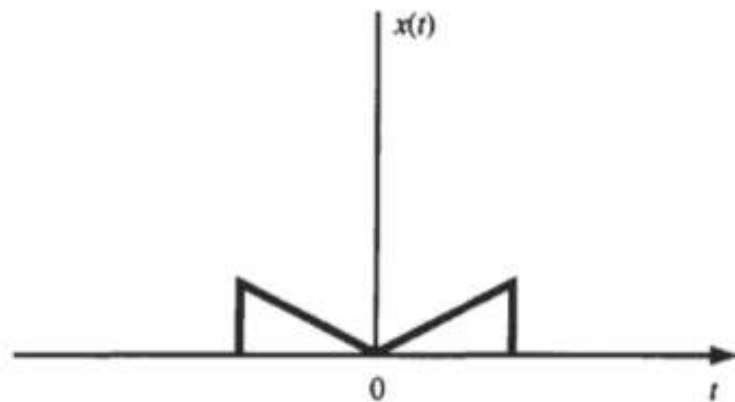
(a)



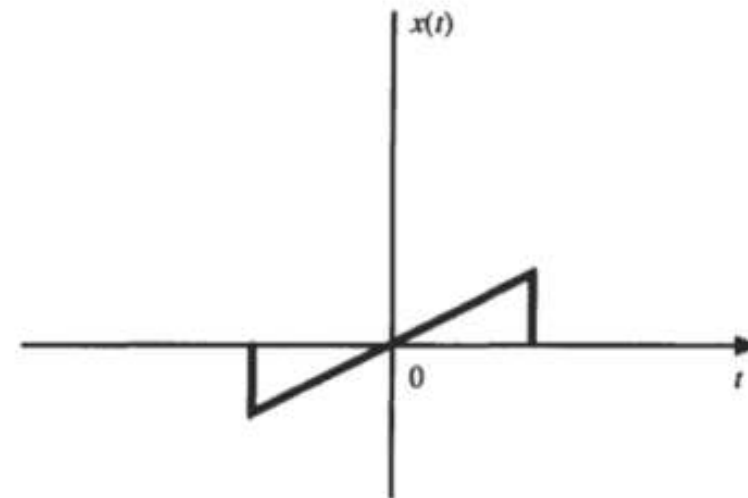
(b)

Fig: Graphical representation of:
(a) Random Signal, **(b)** Noisy Digital Signal

Even and Odd Signals



(a)



(b)

Fig: Graphical representation of:
(a) Even Signal **(b)** Odd Signal



These operations can be classified into two categories,

- Operations performed on the dependent variable and
- Operations performed on the independent variable.



➤ Amplitude scaling:

Let $x(t)$ denote a continuous-time signal. The signal $y(t)$ resulting from amplitude scaling applied to $x(t)$ is defined by

- $y(t) = c x(t)$

Where c is the scaling factor. According to above equation the value of $y(t)$ is obtained by multiplying the corresponding value of $x(t)$ by the scalar c .



➤ Addition:

Let $x_1(t)$ and $x_2(t)$ denote a pair of continuous-time signals. The signal $y(t)$ obtained by the addition of $x_1(t)$ and $x_2(t)$ is defined by

- $y(t) = x_1(t) + x_2(t)$



➤ Multiplication:

Let $x_1(t)$ and $x_2(t)$ denote a pair of continuous-time signals. The signal $y(t)$ resulting from the multiplication of $x_1(t)$ and $x_2(t)$ is defined by

- $y(t) = x_1(t) x_2(t)$



➤ Time scaling:

Let $x(t)$ denote a continuous-time signal. The signal $y(t)$ obtained by scaling the independent variable, time t , by a factor a is defined by

- $y(t) = x(at)$

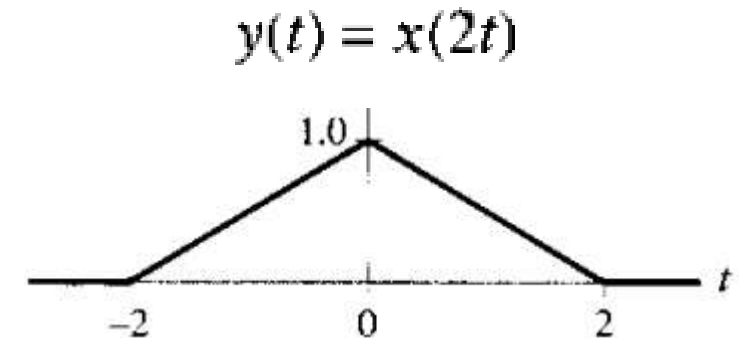
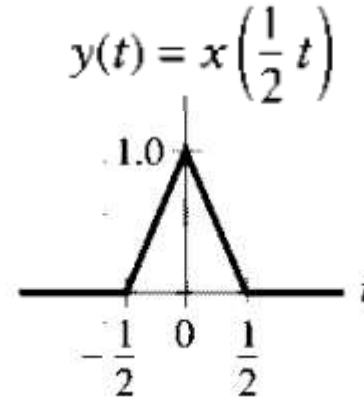
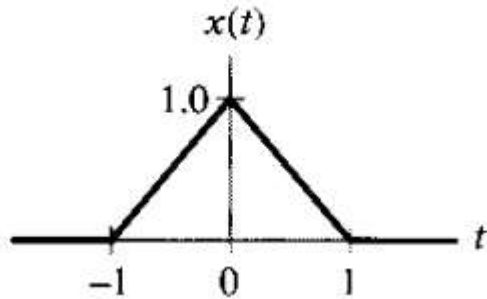


Fig:

- (a) Continuous-time signal $x(t)$, (b) Time expanded version of signal $x(t)$ by factor 2 ($= 1/2$)
(c) Compressed version of signal $x(t)$ by factor 2 ($= 2$),

Operations performed on the independent variable:



➤ Time Reversal (Reflection):

Let $x(t)$ denote a continuous-time signal. Let $y(t)$ denote the signal obtained by replacing time t with $-t$, as shown by

- $y(t) = x(-t)$

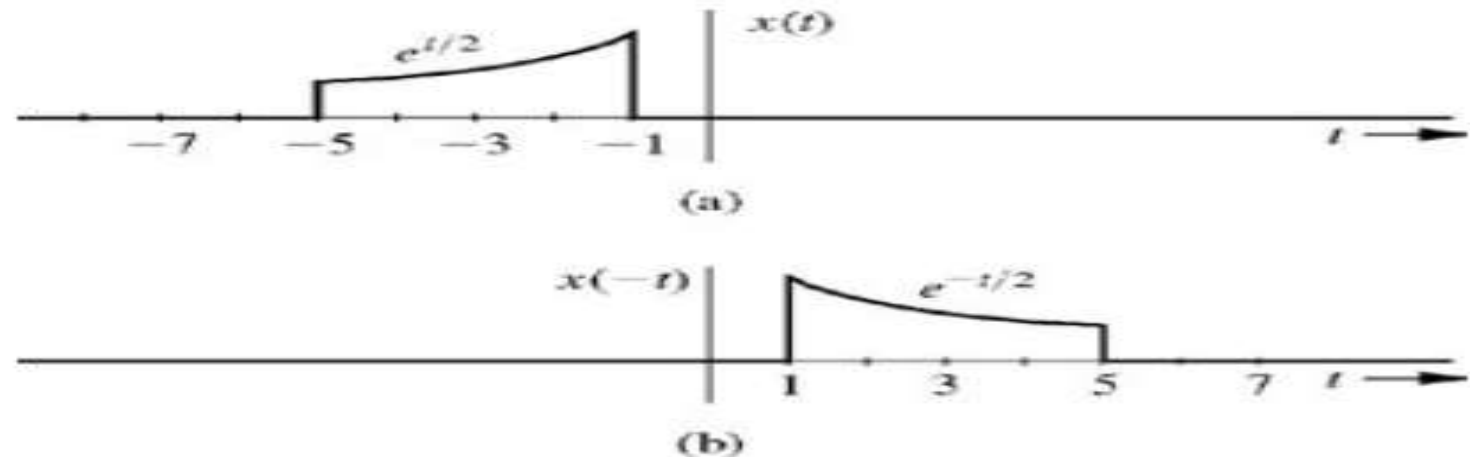


Fig: Operation of reflection:

(a) Continuous-time signal $x(t)$ and **(b)** Reflected version of $x(t)$ about the origin $x(-t)$



➤ Time shifting:

Let $x(t)$ denote a continuous-time signal. The time-shifted version of $x(t)$ is defined by

- $y(t) = x(t - t_0)$

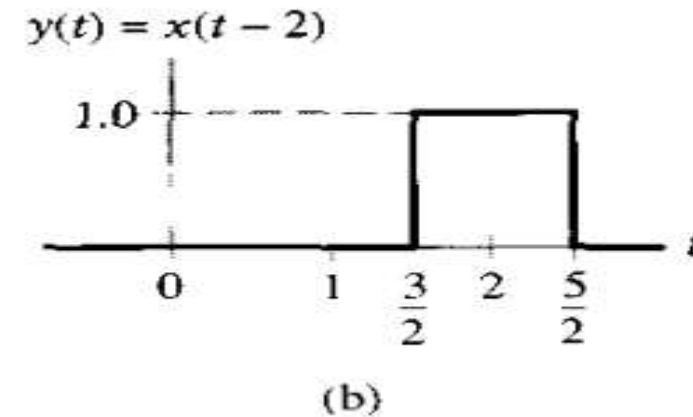
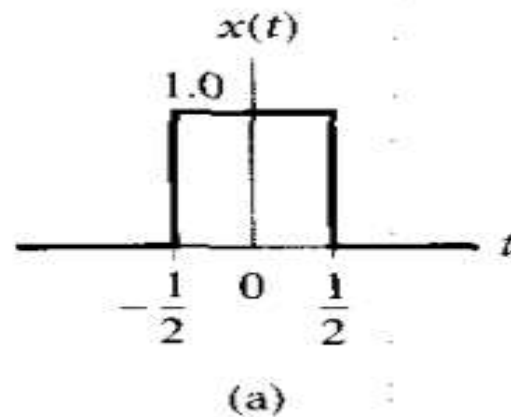


Fig: Time-shifting operation:

(a) Continuous-time signal $x(t)$; and **(b)** Time-shifted version of $x(t)$ by 2 time units



- Sinusoidal Signal.
- Exponential Signal.
- Unit Step Function.
- Unit Ramp Function.
- Unit Impulse Function.

